Logic and Constraint Satisfaction An Introduction

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A Primer on Logic

• What is logic?

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A Primer on Logic

- What is logic?
- "Logic is logic. That's all I say."

The Deacon's Masterpiece Oliver Wendell Holmes, Sr., 1858

Basic Notions	Conjunctive Queries & CSP	Datalog and CSP	Finite-variable Logics and CSP
Outline			











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Vocabularies and Structures

Definition

- Vocabulary σ: a set σ = {R'₁,..., R'_m} of relation symbols of specified arities.
- σ -structure $\mathbf{A} = (A, R_1, \dots, R_m)$: a non-empty set A and relations on A such that $\operatorname{arity}(R_i) = \operatorname{arity}(R'_i), 1 \le i \le m$.
- Finite σ -structure A: universe A is finite

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- Finite σ -structure **A**: universe A is finite

Example

- Graph: $\mathbf{G} = (V, E)$, where E is binary.
- *String:* $S = (\{1, 2, ..., n\}, P)$, where *P* is unary
 - $m \in P \iff$ the *m*-th bit of the string is 1.
 - String 10001 encoded as $(\{1, 2, 3, 4, 5\}, \{1, 5\})$.

Vocabularies and Structures

Example

Every 3-CNF formula can be viewed as a finite structure of the form $\mathbf{A} = (A, R_0, R_1, R_2, R_3)$, where each R_i is a 3-ary relation.

- 3-CNF formula φ with variables x_1, \ldots, x_n
- Structure $\mathbf{A}^{\varphi} = (\{x_1, \dots, x_n\}, R_0^{\varphi}, R_1^{\varphi}, R_2^{\varphi}, R_3^{\varphi})$, where

$$R_0^{\varphi} = \{(x, y, z) : (x \lor y \lor z) \text{ is a clause of } \varphi\}$$

$$\mathsf{R}_1^{\varphi} = \{ (x, y, z) : (\neg x \lor y \lor z) \text{ is a clause of } \varphi \}$$

$$\mathsf{R}_2^{\varphi} = \{(x, y, z) : (\neg x \lor \neg y \lor z) \text{ is a clause of } \varphi\}$$

$$R_3^{\varphi} = \{ (x, y, z) : (\neg x \lor \neg y \lor \neg z) \text{ is a clause of } \varphi \}$$

Queries

Definition

- Class C of structures: a collection of relational σ-structures closed under isomorphisms.
- *k*-ary Query Q on C, where k ≥ 1: a mapping Q with domain C and such that
 - $Q(\mathbf{A})$ is a *k*-ary relation on \mathbf{A} , for $\mathbf{A} \in C$;
 - Q is preserved under isomorphisms, i.e.,
 if h : A → B is an isomorphism, then Q(B) = h(Q(A)).
- Boolean Query Q on C:

a mapping $Q : C \to \{0, 1\}$ preserved under isomorphisms. Thus, Q can be identified with the subclass C' of C, where $C' = \{ \mathbf{A} \in C : Q(\mathbf{A}) = 1 \}.$

Examples of Queries

• PATH OF LENGTH 2: Binary query on graphs $\mathbf{H} = (V, E)$

 $P2(\mathbf{H}) = \{(a, b) \in V^2: \text{ there is a path of length } 2 \text{ from } a \text{ to } b\}.$

• CONNECTIVITY: Boolean query on graphs $\mathbf{H} = (V, E)$

$$CN(\mathbf{H}) = \left\{ egin{array}{c} 1 & ext{if } \mathbf{H} ext{ is connected} \ 0 & ext{otherwise.} \end{array}
ight.$$

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- *k*-Colorability, $k \ge 2$
- 3-SAT (with formulas viewed as structures)

Definability of Queries

Definition

Let L be a logic and C a class of structures

A k-ary query Q on C is L-definable if there is an L-formula φ(x₁,..., x_k) with x₁,..., x_k as free variables and such that for every A ∈ C

$$\mathsf{Q}(\mathsf{A}) = \{(a_1,\ldots,a_k) \in \mathsf{A}^k : \mathsf{A} \models \varphi(a_1,\ldots,a_k)\}.$$

A Boolean query Q on C is L-definable if there is an L-sentence ψ such that for every A ∈ C

$$Q(\mathbf{A}) = \mathbf{1} \iff \mathbf{A} \models \psi.$$

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First-Order Logic

Definition

First-Order Logic FO (on graphs):

- first-order variables: x, y, z, ...
- atomic formulas: E(x, y), x = y
- *formulas:* atomic formulas, Boolean connectives, first-order quantifiers ∃x, ∀x, ∃y, ∀y, ... that range over the nodes of the graph.

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Example

On the class ${\cal G}$ of finite graphs the query PATH OF LENGTH 2 is FO-definable

$$P2(\mathbf{H}) = \{(a,b) \in V^2 : \mathbf{H} \models \exists z (E(a,z) \land E(z,b))\}.$$

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Limitations of First-Order Logic

Fact

- The queries TRANSITIVE CLOSURE, CONNECTIVITY, k-COLORABILITY, $k \ge 2$, are not FO-definable.
- On the class of all finite structures with 4 ternary relations, the query 3-SAT is not first-order definable.

Note: Results about non-definability in FO-logic can be proved using Ehrenfeucht-Fraïssé games.

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The Complexity of Logic

Definition (Vardi, 1982)

The *combined complexity* of *L* is the following decision problem:
 Given a finite structure **B** and an *L*-sentence ψ, does
 B ⊨ ψ?

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 Given a finite structure **B** and an *L*-sentence ψ, does
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- The *data complexity* of *L* is the family of the following decision problems *P*_ψ, one for each fixed *L*-sentence ψ: Given a finite structure **B**, does **B** |= ψ?

The Complexity of Logic

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 Given a finite structure **B** and an *L*-sentence ψ, does
 B ⊨ ψ?
- The *data complexity* of *L* is the family of the following decision problems *P*_ψ, one for each fixed *L*-sentence ψ: Given a finite structure **B**, does **B** |= ψ?
- The expression complexity of L is the family of the following decision problems P_B, one for each fixed finite structure B: Given an L-sentence ψ, does B ⊨ ψ?

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Some Basic Complexity Classes

Definition

- L: problems solvable by a TM in logspace
- NL: problems solvable by a NTM in logspace
- P: problems solvable by a TM in polynomial time
- NP: problems solvable by a NTM in polynomial time
- PSPACE: problems solvable by a TM in polynomial space.

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- P: problems solvable by a TM in polynomial time
- NP: problems solvable by a NTM in polynomial time
- PSPACE: problems solvable by a TM in polynomial space.

Fact

- $L \subseteq NL \subseteq P \subseteq NP \subseteq PSPACE = NPSPACE.$
- $NL \neq PSPACE$
- No other proper containment is known at present.
- Each of them possesses natural complete problems.

The Complexity of Logic

Definition

Let *L* be a logic and C a complexity class.

- The data complexity of L is in C if for each L-sentence ψ, the problem P_ψ is in C.
- The data complexity of L is C-complete if it is in C and there is at least one L-sentence ψ such that P_{ψ} is C-complete.

The Complexity of Logic

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- The data complexity of L is in C if for each L-sentence ψ, the problem P_ψ is in C.
- The data complexity of L is C-complete if it is in C and there is at least one L-sentence ψ such that P_{ψ} is C-complete.
- The expression complexity of L is in C if for each finite structure **B**, the problem P_B is in C.
- The expression complexity of L is C-complete if it is in C and there is at least one finite structure B such that P_B is C-complete.

The Complexity of First-Order Logic

Theorem

- The data complexity of FO is in L.
- Both the expression complexity of FO and the combined complexity of FO are PSPACE-complete.

Proof.

- Fix a first-order sentence ψ. Given a finite structure B: Cycle through all possible instantiations of the quantifiers of ψ in B, keeping track of the number of them using a counter in binary.
- QBF is PSPACE-complete (Stockmeyer 1976).



Basic Notions	Conjunctive Queries & CSP	Datalog and CSP	Finite-variable Logics and CSP
Outline			

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3 Datalog and CSP



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Conjunctive Queries

Definition

 A primitive positive formula (pp-formula) is a FO-formula in prenex normal form built from atomic formulas, ∧, and ∃ only, i.e., it is of the form:

 $(\exists z_1 \dots \exists z_m)\psi(x_1, \dots, x_k, z_1, \dots, z_m),$ where ψ is a conjunction of atomic formulas.

• A conjunctive query is a query definable by a pp-formula.

Conjunctive Queries

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 $(\exists z_1 \dots \exists z_m)\psi(x_1, \dots, x_k, z_1, \dots, z_m),$ where ψ is a conjunction of atomic formulas.

• A conjunctive query is a query definable by a pp-formula.

Example

• PATH OF LENGTH 2 (Binary query) $(\exists z)(E(x_1, z) \land E(z, x_2))$ Can also be written as a rule: $P2(x_1, x_2) := -E(x_1, z), E(z, x_2)$

Conjunctive Queries and Databases

Fact

- Conjunctive queries are the most frequently asked queries in databases (a.k.a. SPJ queries)
- The main construct of SQL expresses conjunctive queries.

Example

Relations $R_1(A, B, C)$, $R_2(B, C, D)$

SELECT	$R_1.A, R_2.D$
FROM	R_1, R_2
WHERE	$R_{1}.B = R_{2}.B$ and $R_{1}.C = R_{2}.C$

This expresses the conjunctive query Q(x, w) definable by $\exists y \exists z (R_1(x, y, z) \land R_2(y, z, w))$

Conjunctive Query Evaluation

A fundamental problem about conjunctive queries

Definition

CONJUNCTIVE QUERY EVALUATION

- Given a CQ Q and a structure **A**, find $Q(\mathbf{A}) = \{(a_1, \dots a_k) : \mathbf{A} \models Q(a_1, \dots, a_k)\}$
- For Boolean queries Q, this becomes:
 Given Q and A, does A ⊨ Q? (is Q(A) = 1?)
- Same problem as the *combined complexity of pp-formulas*.

Example

• Given a graph H, does it contain a triangle?

Conjunctive Query Containment

Another fundamental problem about conjunctive queries

Definition

CONJUNCTIVE QUERY CONTAINMENT

- Given two *k*-ary CQs Q₁ and Q₂, is it true that for every structure A, we have that Q₁(A) ⊆ Q₂(A)?
- For Boolean queries, this becomes:
 Given two Boolean queries Q₁ and Q₂, does Q₁ |= Q₂?
 (does Q₁ logically imply Q₂?)

Example

Is it true that if two nodes of a graph **H** are connected by a path of length 4, then they are also connected by a path of length 3?

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Conjunctive Queries and Homomorphisms

 Chandra and Merlin (1977) showed that:
 CONJUNCTIVE QUERY EVALUATION and
 CONJUNCTIVE QUERY CONTAINMENT are the same problem.

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Conjunctive Queries and Homomorphisms

• Chandra and Merlin (1977) showed that:

CONJUNCTIVE QUERY EVALUATION and CONJUNCTIVE QUERY CONTAINMENT are the *same* problem.

The link is the HOMOMORPHISM PROBLEM:
 Given A and B, does A → B?

Canonical CQs and Canonical Structures

Definition

- Given A = (A, R^A₁,..., R^A_m), the *canonical* CQ of A is the Boolean CQ Q^A with the elements of A as variables and the "facts" of A as conjuncts: ∃x₁...∃x_n(\^m_{i=1} \ t R^A_i(t))
- If Q is a Boolean CQ, then A^Q is the structure with the variables of Q as elements and the conjuncts of Q as "facts".

Example

• If
$$\mathbf{A} = (\{a, b, c\}, \{(a, b), (b, c), (c, a)\}, \text{ then } Q^{\mathbf{A}} \text{ is } \exists x \exists y \exists z (E(x, y) \land E(y, z) \land E(z, x))$$

• If Q is $\exists x \exists y (E(x, y) \land E(x, z)), \text{ then } \mathbf{A}^{Q} = (\{x, y, z), \{(x, y), (x, z)\})$

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Homomorphisms, CQE and CQC

Theorem (Chandra and Merlin, 1977)

For all relational structures **A** and **B**, the following statements are equivalent:

- $\bigcirc \mathbf{A} \to \mathbf{B}$
- ② B ⊨ Q^A
- **3** $Q^{\mathbf{B}} \subseteq Q^{\mathbf{A}}.$

Homomorphisms, CQE and CQC

Alternatively,

Theorem (Chandra and Merlin, 1977)

For all conjunctive queries Q_1 and Q_2 , the following statements are equivalent:

$$\bigcirc \ \ Q_1 \subseteq Q_2$$

$$\bigcirc A^{Q_2} \to A^{Q_1}$$

$$\bigcirc \mathbf{A}^{Q_1} \models Q_2.$$

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Illustration: 3-COLORABILITY

Example

For a graph H, the following are equivalent:

)
$$\mathbf{H} \rightarrow \mathbf{K_3}$$
 (i.e., **H** is 3-colorable)

2
$$\mathbf{K}_3 \models \mathsf{Q}^{\mathsf{H}}$$

 $\textcircled{3} \quad \mathsf{Q}^{\textbf{K}_3} \subseteq \mathsf{Q}^{\textbf{H}}$

(1) \Longrightarrow (2): A hom. $h : \mathbf{H} \to \mathbf{K_3}$ provides witnesses in $\mathbf{K_3}$ for the \exists quantifiers in $Q^{\mathbf{H}}$.

(2) \Longrightarrow (3): If $\mathbf{K}_3 \models \mathbf{Q}^{\mathsf{H}}$ and $\mathbf{A} \models \mathbf{Q}^{\mathsf{K}_3}$, then there are witness functions $h : \mathbf{H} \to \mathbf{K}_3$ and $h^* : \mathbf{K}_3 \to \mathbf{A}$. Then $h^* \circ h : \mathbf{H} \to \mathbf{A}$ provides witnesses in \mathbf{A} for the \exists quantifiers in \mathbf{Q}^{H} .

(3) \Longrightarrow (1): Since $\mathbf{K}_3 \models Q^{\mathbf{K}_3}$, we have $\mathbf{K}_3 \models Q^{\mathbf{H}}$. The witnesses to the \exists quantifiers give a homomorphism from \mathbf{H} to \mathbf{K}_3 .

CSP, Homomorphisms, CQE, and CQC

Fact

- CONSTRAINT SATISFACTION
- THE HOMOMORPHISM PROBLEM
- CONJUNCTIVE QUERY EVALUATION
- CONJUNCTIVE QUERY CONTAINMENT

are the same problem.

CSP, Homomorphisms, CQE, and CQC

Fact

- The combined complexity of conjunctive queries (pp-formulas) coincides with the HOMOMORPHISM PROBLEM (UNIFORM CSP).
- The expression complexity of conjunctive queries (pp-formulas) coincides with the family of problems CSP(B), where

$$\mathrm{CSP}(\mathbf{B}) = \{\mathbf{A} : \mathbf{A} \to \mathbf{B}\} = \{\mathbf{A} : \mathbf{B} \models \mathbf{Q}^{\mathbf{A}}\}.$$

 Both the combined complexity and the expression complexity of conjunctive queries are NP-complete. (contrast with FO.)

Tractability of CSP via Logic

Fact

• The complexity of CSP(**B**) depends on **B**:

- CSP(K₃) is 3-COLORABILITY, hence is NP-complete.
- CSP(K₂) is 2-COLORABILITY, hence is in P.

Approach

- Use logic to identify tractable (polynomial-time solvable) cases of CSP(B).
- Study when CSP(B) is definable in some logic L whose data complexity is in P.

CSP and Unions of Conjunctive Queries

Definition

For every structure **B**, let

$$\neg CSP(\mathbf{B}) = \{\mathbf{A} : \mathbf{A} \neq \mathbf{B}\}.$$

Fact

For every structure B:

• $\neg CSP(B)$ is closed under homomorphisms.

Moreover,

$$\neg CSP(\mathbf{B}) = \{\mathbf{A} : \mathbf{A} \models \bigvee_{\mathbf{D} \neq \mathbf{B}} \mathbf{Q}^{\mathbf{D}}\},\$$

i.e., $\neg CSP(B)$ is definable by an infinite union of conjunctive queries.

CSP and Unions of Conjunctive Queries

Definition

- $L_{\infty\omega}$ is the extension of FO with infinitary disjunctions and infinitary conjunctions.
- $\exists L^+_{\infty\omega}$ is the existential positive fragment of $L_{\infty\omega}$.

Approach

• Thus, for every structure **B**, we have that $\neg CSP(B)$ is $\exists L^+_{\infty\omega}$ -definable, since

$$\neg \text{CSP}(\mathbf{B}) = \{\mathbf{A} : \mathbf{A} \models \bigvee_{\mathbf{D} \neq \mathbf{B}} \mathbf{Q}^{\mathbf{D}} \}.$$

• Study when $\neg CSP(B)$ is definable in a tractable fragment of $\exists L^+_{\infty\omega}$.

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CSP and First-Order Logic

Fact

Assume that **B** is a structure such that $\neg \text{CSP}(\mathbf{B})$ is definable by a finite union of conjunctive queries (i.e., $\neg \text{CSP}(\mathbf{B}) = \bigvee_{i=1}^{m} Q^{\mathbf{D}_i}$). Then $\text{CSP}(\mathbf{B})$ is FO-definable; hence, it is in P.

CSP and First-Order Logic

Fact

Assume that **B** is a structure such that $\neg \text{CSP}(\mathbf{B})$ is definable by a finite union of conjunctive queries (i.e., $\neg \text{CSP}(\mathbf{B}) = \bigvee_{i=1}^{m} Q^{\mathbf{D}_i}$). Then $\text{CSP}(\mathbf{B})$ is FO-definable; hence, it is in P.

Theorem (Atserias, 2005)

For every structure **B**, the following statements are equivalent.

- CSP(B) is FO-definable.
- CSP(B) is definable by a finite union of conjunctive queries.

CSP and First-Order Logic

Example (Gallai-Hesse-Roy Theorem, circa 1965)

Let \mathbf{T}_k be the linear order with k elements and \mathbf{P}_{k+1} be the directed path with k + 1 elements. Then, for every directed graph **G**, we have that

$$\mathbf{G} \to \mathbf{T}_k \iff \mathbf{P}_{k+1} \not\to \mathbf{G}.$$

Consequently,

$$\neg \operatorname{CSP}(\mathbf{T}_k) = \{ \mathbf{G} : \mathbf{G} \models \mathbf{Q}^{\mathbf{P}_{k+1}} \}.$$

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Beyond First-Order Logic

Fact

- CSP(**K**₂) is 2-COLORABILITY.
- CSP(**K**₂) is in P, but it is not FO-definable.
- Hence, ¬CSP(K₂) is definable by an infinite union of conjunctive queries, but it is not definable by any finite union of conjunctive queries.

Question

Can the tractability of $CSP(\mathbf{K}_2)$ be explained via definability in a logic other than FO?

Basic Notions	Conjunctive Queries & CSP	Datalog and CSP	Finite-variable Logics and CSP
Outline			





3 Datalog and CSP

Finite-variable Logics and CSP

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Tractability via Definability in Datalog

Fact (Feder and Vardi, 1993)

Definability of $\neg CSP(B)$ in Datalog is a unifying explanation for many tractability results about CSP(B), including $CSP(K_2)$.

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Note: Recall that every CQ can be written as a rule: $P2(x_1, x_2) := -E(x_1, z), E(z, x_2)$

Definition

- Datalog = Conjunctive Queries + Recursion
 Function, negation-free, and ≠-free logic programs
- A Datalog program is a finite set of rules given by conjunctive queries

$$T(\overline{x}) := S_1(\overline{y}_1), \ldots, S_r(\overline{y}_r).$$

Intensional DB predicates (IDBs): those that occur both in the *heads* and the *bodies* of rules (recursive predicates). Extensional DB predicates (EDBs): all other predicates.

Example (TRANSITIVE CLOSURE Query TC)

 $TC(\mathbf{H}) = \{(a, b) : \text{there is a path from } a \text{ to } b \text{ in } \mathbf{H}\}.$

A Datalog program for TC (linear Datalog)

$$\begin{array}{rcl} S(x,y) & :- & E(x,y) \\ S(x,y) & :- & E(x,z), S(z,y) \end{array}$$

Another Datalog program for TC (non-linear Datalog)

$$\begin{vmatrix} S(x,y) &:- E(x,y) \\ S(x,y) &:- S(x,z), S(z,y) \end{vmatrix}$$

• E is the EDB.

• S is the IDB; it defines TC.

Semantics of Datalog Programs

Example

A Datalog program for TC

$$S(x, y) :- E(x, y)$$

 $S(x, y) :- E(x, z), S(z, y)$

Operational Semantics: "Bottom-up" Evaluation

$$egin{array}{rcl} & S^0 & = & \emptyset \ & S^{m+1} & = & \{(a,b)): \exists z (E(a,z) \wedge S^m(z,b))\} \end{array}$$

Fact: The following statements are true:

$$S^m = \{(a, b) : \text{there is a path of length} \le m \text{ from } a \text{ to } b\}$$

 $TC = \bigcup_m S^m = S^{|V|}.$

Datalog and 2-Colorability

Example

- $CSP(K_2) = 2$ -Colorability.
- Recall that a graph is 2-colorable if and only if it does not contain an odd cycle.
- Datalog program for NON-2-COLORABILITY:

$$\begin{array}{rcl} O(X,Y) & :- & E(X,Y) \\ O(X,Y) & :- & O(X,Z), E(Z,W), E(W,Y) \\ Q & :- & O(X,X) \end{array}$$

Data Complexity of Datalog

Theorem

- Every Datalog query is definable by an "effective and uniform" union of conjunctive queries.
- Every Datalog query is in P.
- The data complexity of Datalog is P-complete.

Proof.

- The "bottom-up" evaluation of Datalog programs converges in polynomially-many steps.
- Each iteration is definable by a finite union of conjunctive queries.
- HORN 3-UNSAT is P-complete and expressible in Datalog.

Horn 3-SAT and Datalog

Fact (HORN 3-UNSAT is expressible in Datalog)

• Horn 3-CNF formula φ viewed as a finite structure

 $\mathbf{A}^{\varphi} = (\{x_1, \ldots, x_n\}), U, P, N), \text{ where }$

- U is the set of unit clauses x
- *P* is the set of clauses $(\neg x \lor \neg y \lor z)$
- *N* is the set of clauses $(\neg x \lor \neg y \lor \neg z)$.
- Datalog program for HORN 3-UNSAT: encodes the unit propagation algorithm for Horn Satisfiability.

$$\begin{array}{rcl} T(z) & :- & U(z) \\ T(z) & :- & P(x,y,z), T(x), T(y) \\ Q & :- & N(x,y,z), T(x), T(y), T(z) \end{array}$$

Provably non-linearizable.

Tractability via Definability in Datalog

Fact (Feder and Vardi, 1993)

Definability of $\neg CSP(B)$ in Datalog is a unifying explanation for many tractability results about CSP(B).

Theorem (Feder and Vardi, 1993)

If B = (B, R₁,..., R_k) is such that Pol({R₁,..., R_k}) contains a near-unanimity function, then ¬CSP(B) is Datalog-definable.

Special Case: 2-SAT

If B = (B, R₁,..., R_k) is such that Pol({R₁,..., R_k}) contains a semi-lattice function, then ¬CSP(B) is Datalog-definable.

Special Case: HORN k-SAT, DUAL HORN k-SAT, $k \ge 2$.

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Logics with Finitely Many Variables

An old, but fruitful, idea: the number of variables is a resource.

Definition

- FO^k : FO-formulas with at most k variables.
- L^k : FO^k-formulas built from atomic formulas, \wedge , and \exists only.
- Note: Each L^k-formula defines a conjunctive query.

Logics with Finitely Many Variables

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- FO^k : FO-formulas with at most k variables.
- L^k : FO^k-formulas built from atomic formulas, \wedge , and \exists only.
- Note: Each L^k-formula defines a conjunctive query.

Example

• $P^n(x, y)$: there is a path of length *n* from *x* to *y*.

Logics with Finitely Many Variables

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Definition

- FO^k : FO-formulas with at most k variables.
- L^k : FO^k-formulas built from atomic formulas, \wedge , and \exists only.
- Note: Each L^k-formula defines a conjunctive query.

Example

- $P^n(x, y)$: there is a path of length *n* from *x* to *y*.
- $P^n(x, y)$ is L³-definable.

$$\begin{array}{lll} \mathcal{P}^1(x,y) &\equiv & \mathcal{E}(x,y) \\ \mathcal{P}^{n+1}(x,y) &\equiv & \exists z (\mathcal{E}(x,z) \land \exists x ((x=z) \land \mathcal{P}_n(x,y))). \end{array}$$

k-Datalog

Definition

A *k*-Datalog program is a Datalog program in which each rule $t_0 := -t_1, \ldots, t_m$ has at most *k* distinct variables.

Example

NON 2-COLORABILITY revisited

$$\begin{array}{rcl} O(X,Y) & :- & E(X,Y) \\ O(X,Y) & :- & O(X,Z), E(Z,W), E(W,Y) \\ Q & :- & O(X,X) \end{array}$$

- Therefore, NON 2-COLORABILITY is definable in 4-Datalog.
- Exercise: NON 2-COLORABILITY is definable in 3-Datalog.

Datalog and Finite-Variable Logics

Theorem (K ... and Vardi, 1990)

- Every k-Datalog definable query is also definable by a formula of the form V_{n≥1} ψ_n, where ψ_n is an L^k-formula.
- Consequently, *k*-Datalog $\subseteq \exists L_{\infty\omega}^{k,+}$.

Note

In general, *k*-Datalog is a proper fragment of $\exists L_{\infty\omega}^{k,+}$. (The latter can express non-recursive queries using arbitrary infinite disjunctions.)

Datalog, Finite-Variable Logics, and CSP

Theorem (K ... and Vardi, 1998)

For every **B** and every $k \ge 1$, the following are equivalent:

- \neg CSP(**B**) is definable in *k*-Datalog.
- ② ¬CSP(**B**) is definable by a formula of the form $\bigvee_{n\geq 1} \psi_n$, where each ψ_n is an L^{*k*}-formula.

▶
$$\neg$$
CSP(**B**) is definable in $\exists L_{\infty\omega}^{k,+}$.

Note

Recall that

$$\neg \text{CSP}(\mathbf{B}) = \{\mathbf{A} : \mathbf{A} \models \bigvee_{\mathbf{D} \neq \mathbf{B}} \mathbf{Q}^{\mathbf{D}} \}$$

and each Q^D is a conjunctive query.

CSP and Logic

Summary

For every structure **B** and for every $k \ge 1$:

- ¬CSP(B) is definable by an (infinite) union of conjunctive queries.
- ¬CSP(B) is FO-definable if and only if it is definable by a finite union of conjunctive queries.
- ¬CSP(B) is definable in k-Datalog if and only if it is definable by an (infinite) union of conjunctive queries each of which is L^k-definable.

Existential k-Pebble Games

Spoiler and Duplicator play on two structures **A** and **B**. Each player uses k pebbles, labeled 1, ..., k. In each move,

- Spoiler places a pebble on or removes a pebble from an element of **A**.
- Duplicator tries to duplicate the move on **B** using the pebble with the same label.

- Spoiler wins the (∃, k)-pebble game if at some point the mapping a_i → b_i, 1 ≤ i ≤ l, is not a partial homomorphism.
- Duplicator wins the (∃, k)-pebble game if the above never happens.

Fact (Cliques of Different Size)

Let \mathbf{K}_k be the *k*-clique. Then

- Duplicator wins the (\exists, k) -pebble game on \mathbf{K}_k and \mathbf{K}_{k+1} .
- Spoiler wins the (\exists, k) -pebble game on \mathbf{K}_k and \mathbf{K}_{k-1} .

Example



Winning Strategies in the (\exists, k) -Pebble Game

Definition

A *winning strategy* for the Duplicator in the (\exists, k) -pebble game is a non-empty set \mathcal{I} of partial homomorphisms from **A** to **B** such that

If *f* ∈ *I* and *h* ⊆ *f*, then *h* ∈ *I* (*I* is closed under subfunctions).

If *f* ∈ *I* and |*f*| < *k*, then for every *a* ∈ *A*, there is *g* ∈ *I* so that *f* ⊆ *g* and *a* ∈ dom(*g*).
(*I* has the *forth property up to k*)

Fact

If $\mathbf{A} \to \mathbf{B}$, then, for every $k \ge 1$, the Duplicator wins the (\exists, k) -pebble game on \mathbf{A} and \mathbf{B} .

k-Datalog and (\exists, k) -Pebble Games

Theorem (K ... and Vardi)

- Let Q be a query definable in ∃L^{k,+}_{∞ω}. If A satisfies Q and the Duplicator wins the (∃, k)-pebble game on A and B, then also B satisfies Q.
- There is a polynomial-time algorithm to decide whether, given two finite structures A and B, the Spoiler or the Duplicator wins the (∃, k)-pebble game on A and B.
- For every fixed finite structure B, there is a *k*-Datalog program that expresses the query: given a finite structure A, does the Spoiler win the (∃, k)-game on A and B?

k-Datalog, $\exists L_{\infty\omega}^{k,+}$, (\exists, k) -pebble games, and CSP

Theorem

Let k be a positive integer and **B** a finite structure. Then the following statements are equivalent:

- \neg CSP(**B**) is definable in *k*-Datalog.
- **2** \neg CSP(**B**) is definable in $\exists L_{\infty\omega}^{k,+}$.
- \bigcirc CSP(**B**) =

 $\{A : Duplicator wins the (\exists, k) \text{-pebble game on } A \text{ and } B\}.$

Note

Single *canonical* polynomial-time algorithm for all CSP(B)'s that are definable in *k*-Datalog: Determine the winner in the (\exists, k) -pebble game.

The Hierarchy Problem for Datalog-definable CSPs

Problem

Prove or disprove:

For every $k \ge 4$, there is a directed graph \mathbf{G}_k such that

- \neg CSP(**G**_{*k*}) is definable in *k*-Datalog;
- \neg CSP(**G**_{*k*}) is not definable in (*k* 1)-Datalog.

Note

- NON 2-COLORABILITY is definable in 3-Datalog, but not in 2-Datalog.
- All ¬CSP(G)'s presently known to be definable in Datalog are actually definable in 3-Datalog.

The Meta-problem for Datalog-definable CSPs

Problem

Determine whether or not the following problems are decidable:

- Given a structure **B**, is \neg CSP(**B**) definable in Datalog?
- Given a structure B, is ¬CSP(B) definable in *k*-Datalog? (Here *k* is a fixed positive integer.)

Theorem (Larose, Loten, and Tardif, 2006)

The following problem is NP-complete: Given a structure **B**, is CSP(**B**) definable in first-order logic?



"Logic is in the eye of the logician."

Outrageous Acts and Everyday Rebellions Gloria Steinem, 1986.

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