

# LOWER BOUNDS & COMPUTATIONAL COMPLEXITY

CONSIDER THE SET OF ALL ALGORITHMS (KNOWN & UNKNOWN) WHICH SOLVE SOME PROBLEM  $P$  IN ALL ITS INSTANCES.

OUR GOALS ARE TWOFOLD:

- 1.) Find an algorithm which solves  $P$  in (worst case) time  $O(f(n))$  for some function  $f(n)$  which we aim to reduce as far as possible.
- 2.) Prove that any algorithm which solves  $P$  must run in (worst case) time  $\Omega(g(n))$  for some function  $g(n)$  which we aim to increase as far as possible.

HERE  $n$  DENOTES THE 'SIZE' OF AN INSTANCE OF PROBLEM  $P$ .

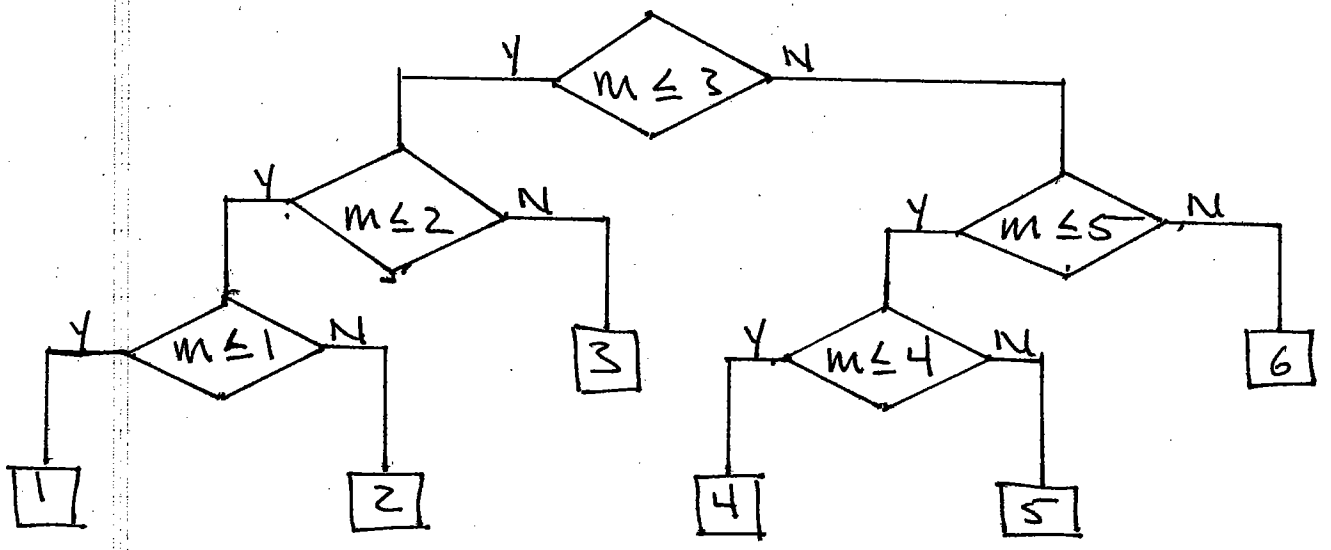
WE ARE HAPPY WHEN  $f(n) = \Theta(g(n))$  FOR THEN WE KNOW WE HAVE THE BEST POSSIBLE ALGORITHM TO SOLVE  $P$  (APART FROM IMPROVEMENTS IN HIDDEN CONSTANT.)

(1) is called Algorithmics by some authors, while (2) is the theory of computational complexity. The function  $g(n)$  in (2) is called a lower bound on the complexity of problem  $P$ .

Decision Trees / Information Theoretic Lower Bound

Ex. Let  $m$  be an integer in the range  $1 \leq m \leq 6$ . Problem: Determine the value of  $m$  by asking a sequence of yes/no questions.

This problem is similar to binary search!



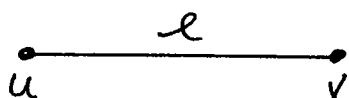
Worst case # comp. = 3

Avg. case # comp. =  $\frac{3+3+2+3+3+2}{6} = \frac{16}{6} = 2.66$

APPARENTLY THE ANSWER CAN BE OBTAINED BY ASKING NO MORE THAN 3 QUESTIONS. (will 2 suffice?)

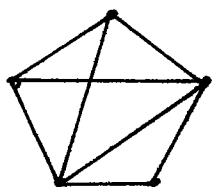
REVIEW: GRAPHS - TREES - ROOTED TREES.

A GRAPH  $G = (V, E)$  is a pair of sets called VERTICES ( $V$ ) and EDGES ( $E$ ), EACH EDGE JOINS A (UNIQUE) PAIR OF (DISTINCT) VERTICES. TWO VERTICES WHICH ARE JOINED BY AN EDGE ARE CALLED ADJACENT



A PATH in  $G$  is a SEQUENCE OF CONSECUTIVELY ADJACENT VERTICES.  $G$  is CALLED CONNECTED IF EVERY PAIR OF VERTICES IN  $G$  ARE JOINED BY A PATH. A cycle is a closed path, i.e. a path in which the initial and terminal vertices are identical.  $G$  is CALLED Acyclic if it contains NO cycle. A TREE is a CONNECTED ACYCLIC GRAPH.

GRAPH:



TREE:

