

# Mechanical Components

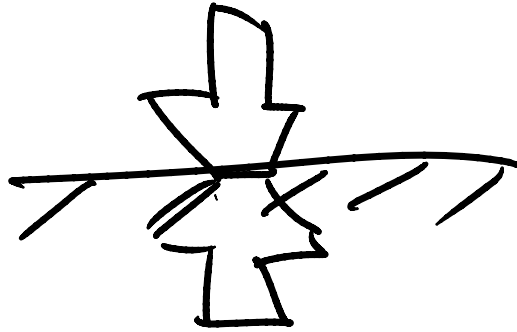
Cyrus Bazeghi  
Winter 2010

مکانیک  
سیستم  
ساز

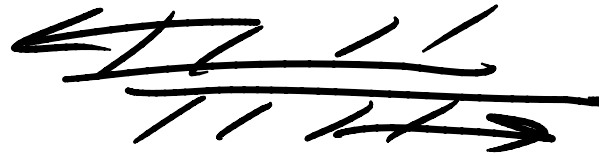


# Physics Review: Forces

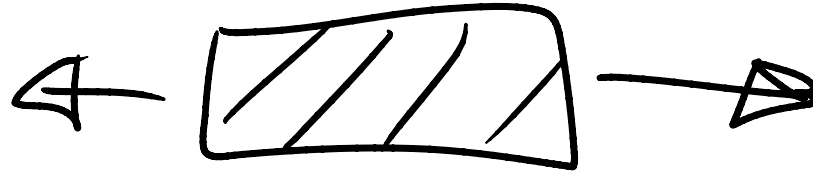
- Normal



- Sheer



- Tensile



- Compressive

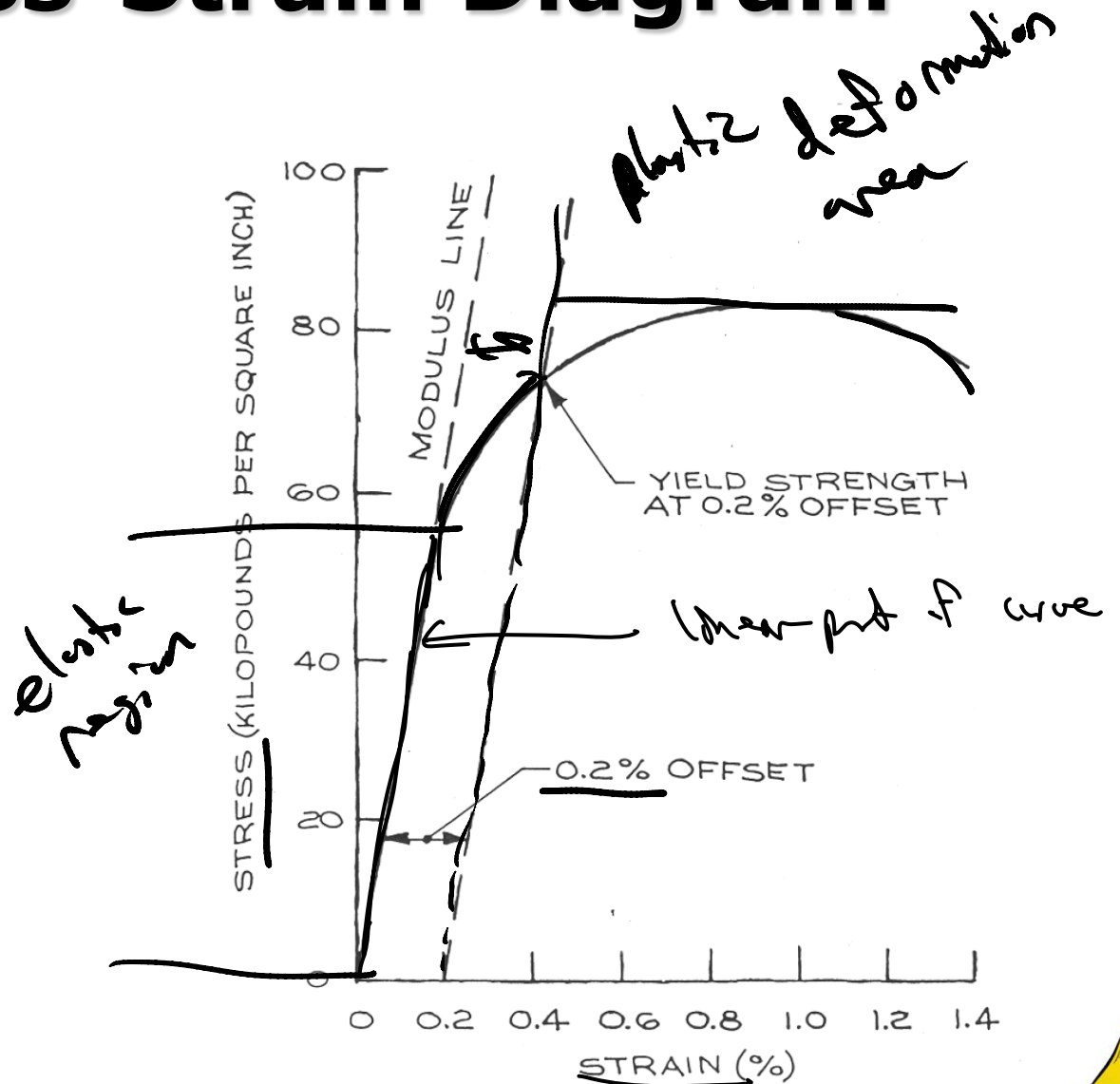


# Material Properties Terms

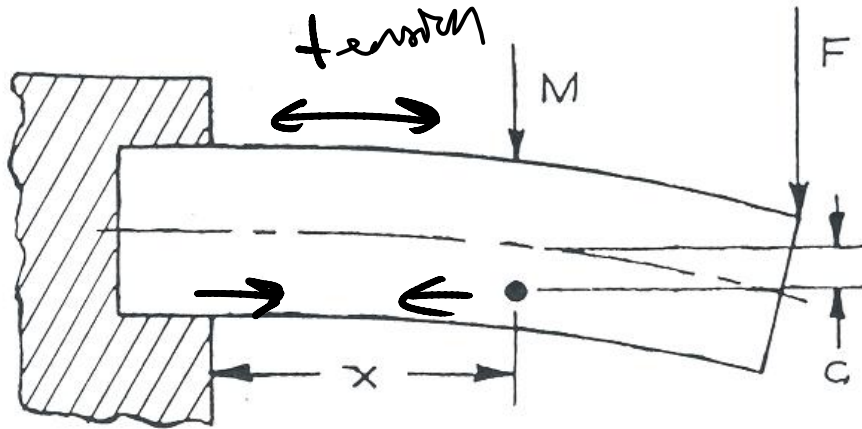
- Stress –  $\frac{\text{Force}}{\text{area}}$
- Strain – elongation (normalized)  
 $\frac{\Delta L}{L} (\%)$
- Modulus of Elasticity – Young's Modulus  
spring constant of material  
stress vs. strain slope  
"Marks Handbook of Mechanical Properties"



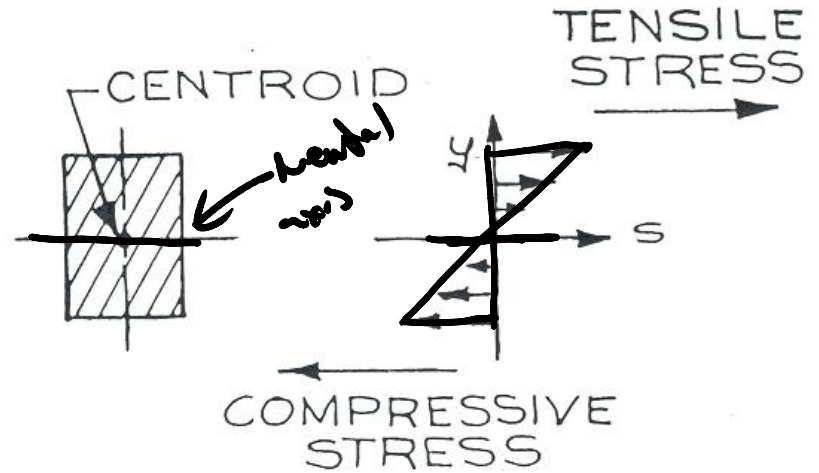
# Stress-Strain Diagram



# Beams in Bending

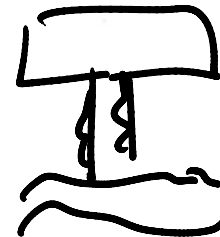
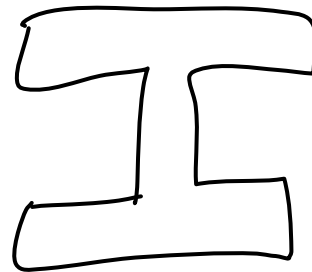


(a)



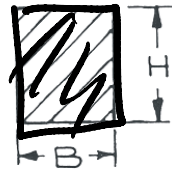
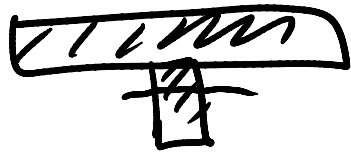
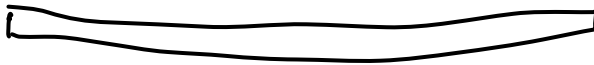
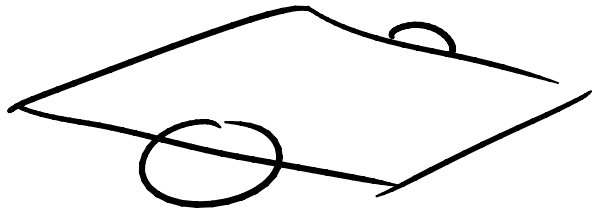
(b)

(c)

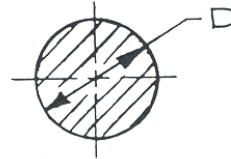


# Shape is Important

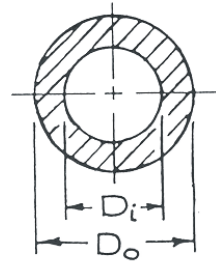
$I$  = moment of inertia



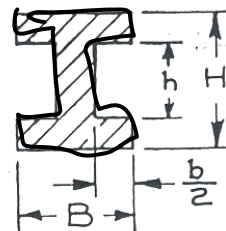
$$I = \frac{BH^3}{12}$$



$$I = \frac{\pi D^4}{64}$$



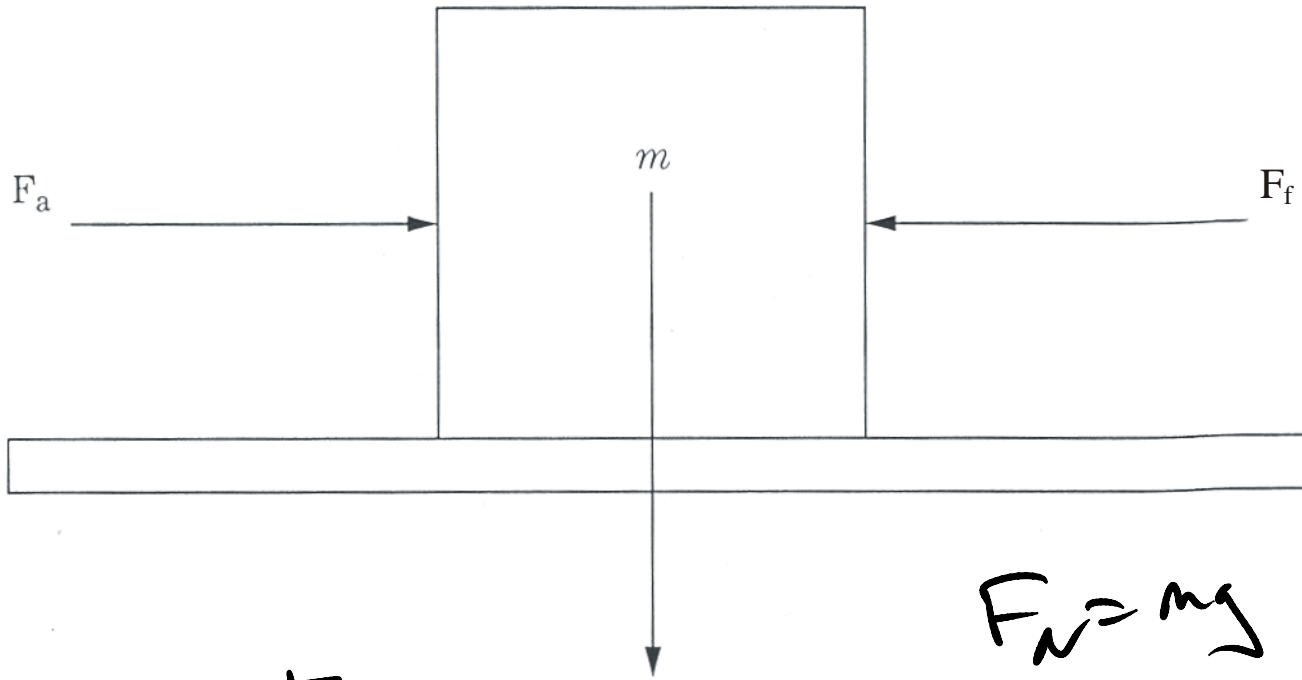
$$I = \frac{\pi}{64} (D_o^4 - D_i^4)$$



$$I = \frac{1}{12} (BH^3 - bh^3)$$



# Friction



$$F_f = \mu F_n$$

$$F_n = m g_0$$

$$F_n = m g$$

$$\mu_s < 1$$

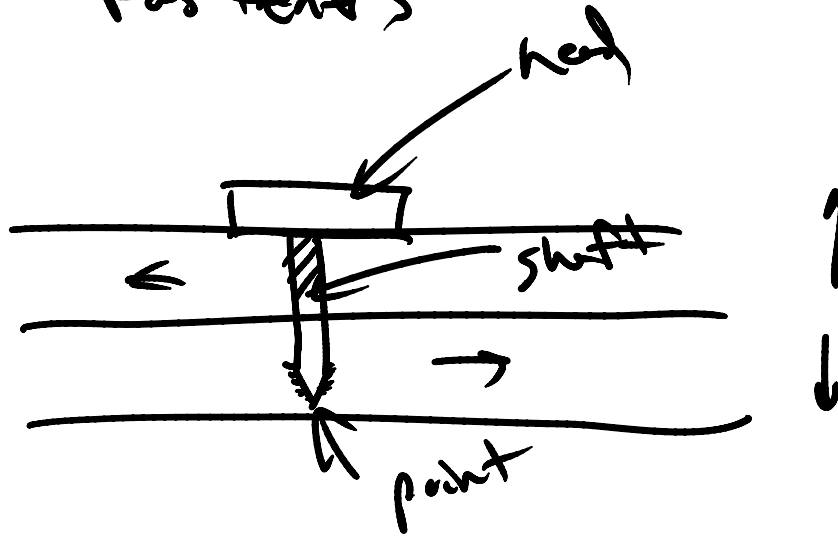
$\mu_s$  - static

$\mu_k$  - kinetic - dynamic



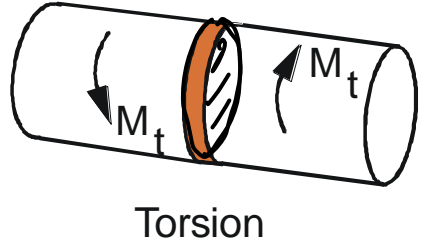
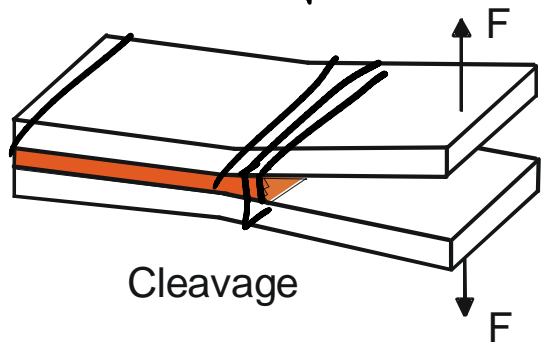
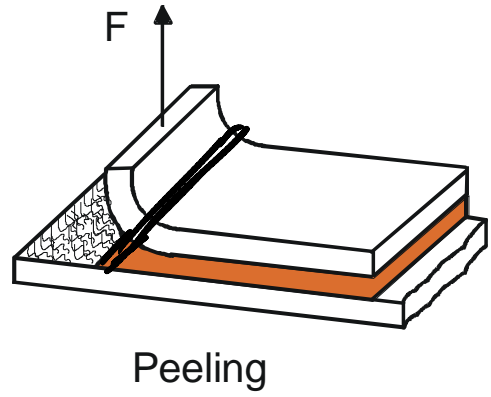
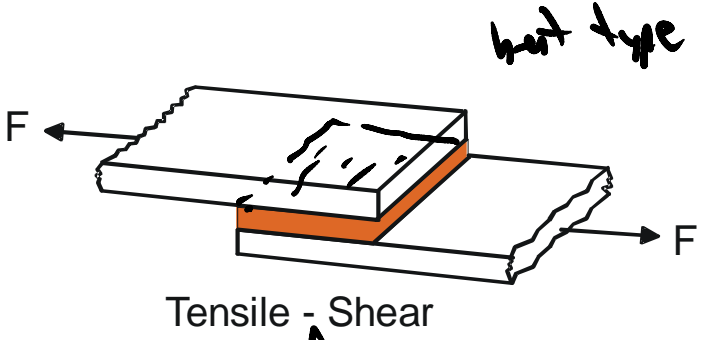
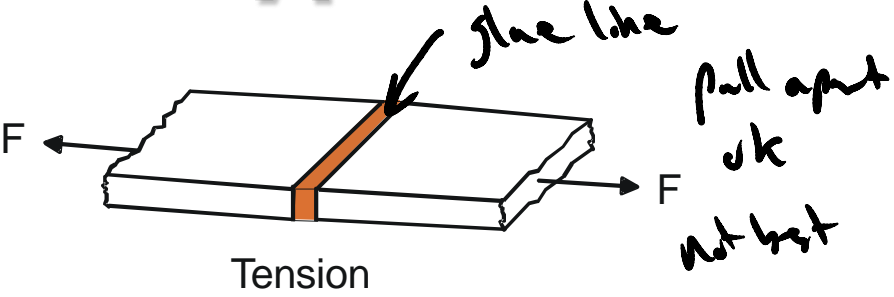
# Fastening Methods

- Adhesives
- Threaded Fasteners
- Nails



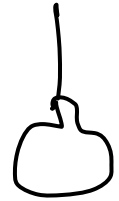


# Types of Adhesive Loading



# Adhesive Types

Non-Filling - solvent (acrylic cement)



\* Needs smooth, clean surface  
to contact w/o voids

Cyano-acrylate (super glue)  
"Zip-a-gap" or "zip-kicker"

Filling type - 1. solid or semi-liquid - solidify to make bond

- Elmers - (Aliphatic Cement)

- rough up the area - increase surface area

- glue sticks

- glue gun-kind of weak

- caulks (silicon)

- rubber cement - ok

- liquid nails

Contact cement - better

- Epoxy - very strong



# Threaded Fasteners: Machine Screws

Handwritten notes on the left side of the page:

- phillips (with a cross symbol)
- Torx (with a star symbol)
- Square (with a square symbol)
- pointy? (with a square symbol)

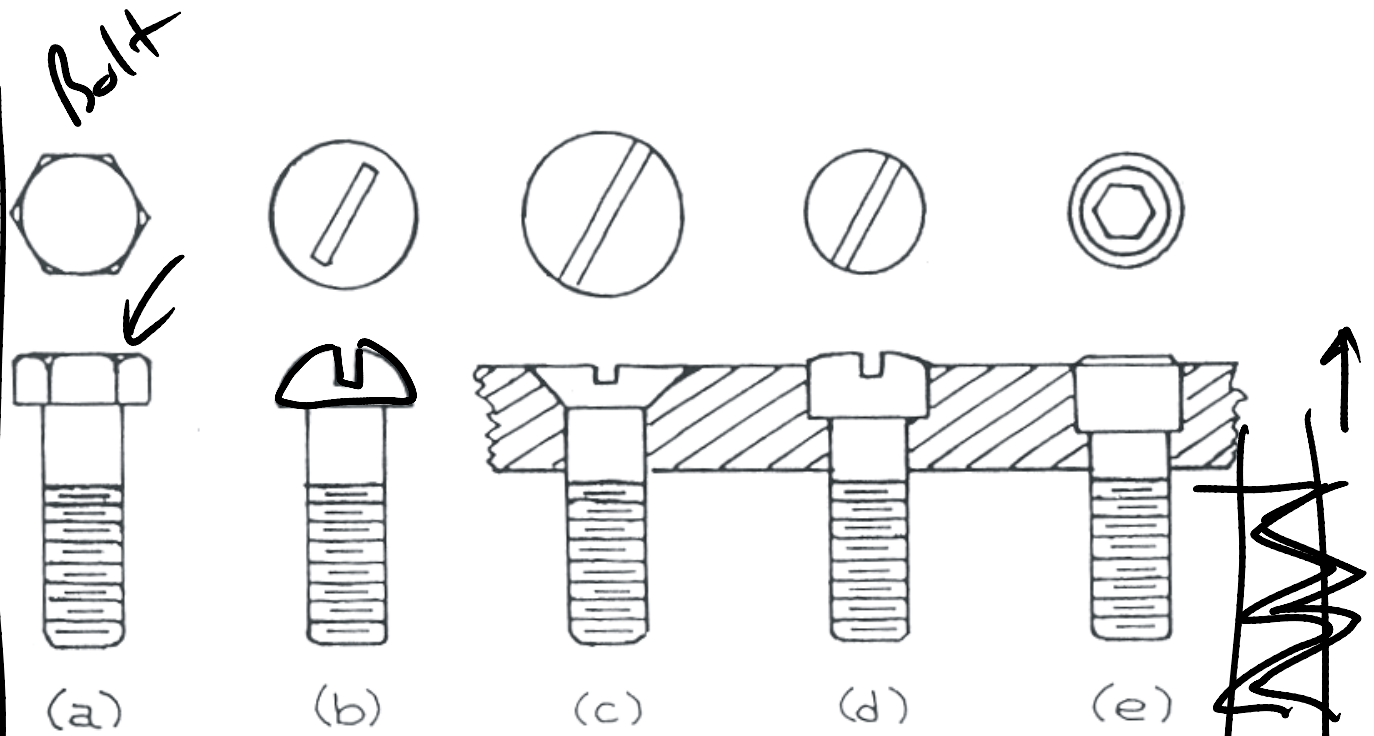
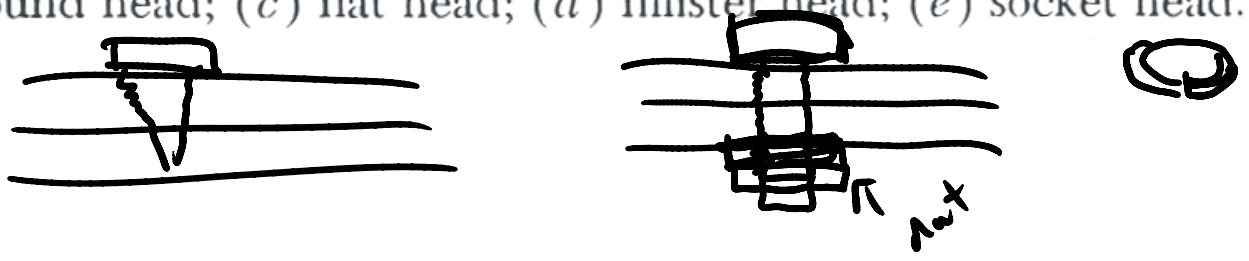


Figure 1.14 Common machine screws: (a) hex head; (b) round head; (c) flat head; (d) fillister head; (e) socket head.



# Standard Screw Sizes

Table 1.5 AMERICAN STANDARD UNIFIED AND AMERICAN NATIONAL THREADS

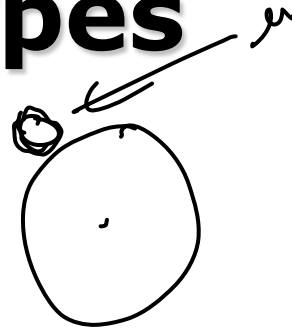
Size (nominal diameter)	<u>Coarse</u> (NC, UNC)		<u>Fine</u> (NF, UNF)	
	Threads per Inch	Tap Drill <sup>a</sup>	Threads per Inch	Tap Drill <sup>a</sup>
0 (0.060)			80	$\frac{3}{64}$
1 (0.073)	64	No. 53	72	No. 53
2 (0.086)	56	No. 50	64	No. 50
3 (0.099)	48	No. 47	56	No. 45
4 (0.112)	40	No. 43	48	No. 42
5 (0.125)	40	No. 38	44	No. 37
6 (0.138)	32	No. 36	40	No. 33
8 (0.164)	32	No. 29	36	No. 29
10 (0.190)	24	No. 25	32	No. 21
12 (0.216)	24	No. 16	28	No. 14
$\frac{1}{4}$	20	No. 7	28	No. 3
$\frac{5}{16}$	18	Let. F	24	Let. I
$\frac{3}{8}$	16	$\frac{5}{16}$	24	Let. Q
$\frac{7}{16}$	14	Let. U	20	$\frac{25}{64}$
$\frac{1}{2}$	13	$\frac{27}{64}$	20	$\frac{29}{64}$
$\frac{9}{16}$	12	$\frac{31}{64}$	18	$\frac{33}{64}$
$\frac{5}{8}$	11	$\frac{17}{32}$	18	$\frac{37}{64}$
$\frac{3}{4}$	10	$\frac{21}{32}$	16	$\frac{11}{16}$
$\frac{7}{8}$	9	$\frac{49}{64}$	14	$\frac{13}{16}$
1	8	$\frac{7}{8}$	12	$\frac{59}{64}$

Handwritten notes: "UNC" and "UNF" with arrows pointing to the Coarse and Fine columns respectively. A large downward arrow is on the left side of the table. A horizontal line is drawn under "No. 7" and "Let. U". A horizontal line is drawn under "No. 3" and "Let. I". A downward arrow points to "Let. Q" with the word "letters" written next to it.



# Drive Types

Friction —



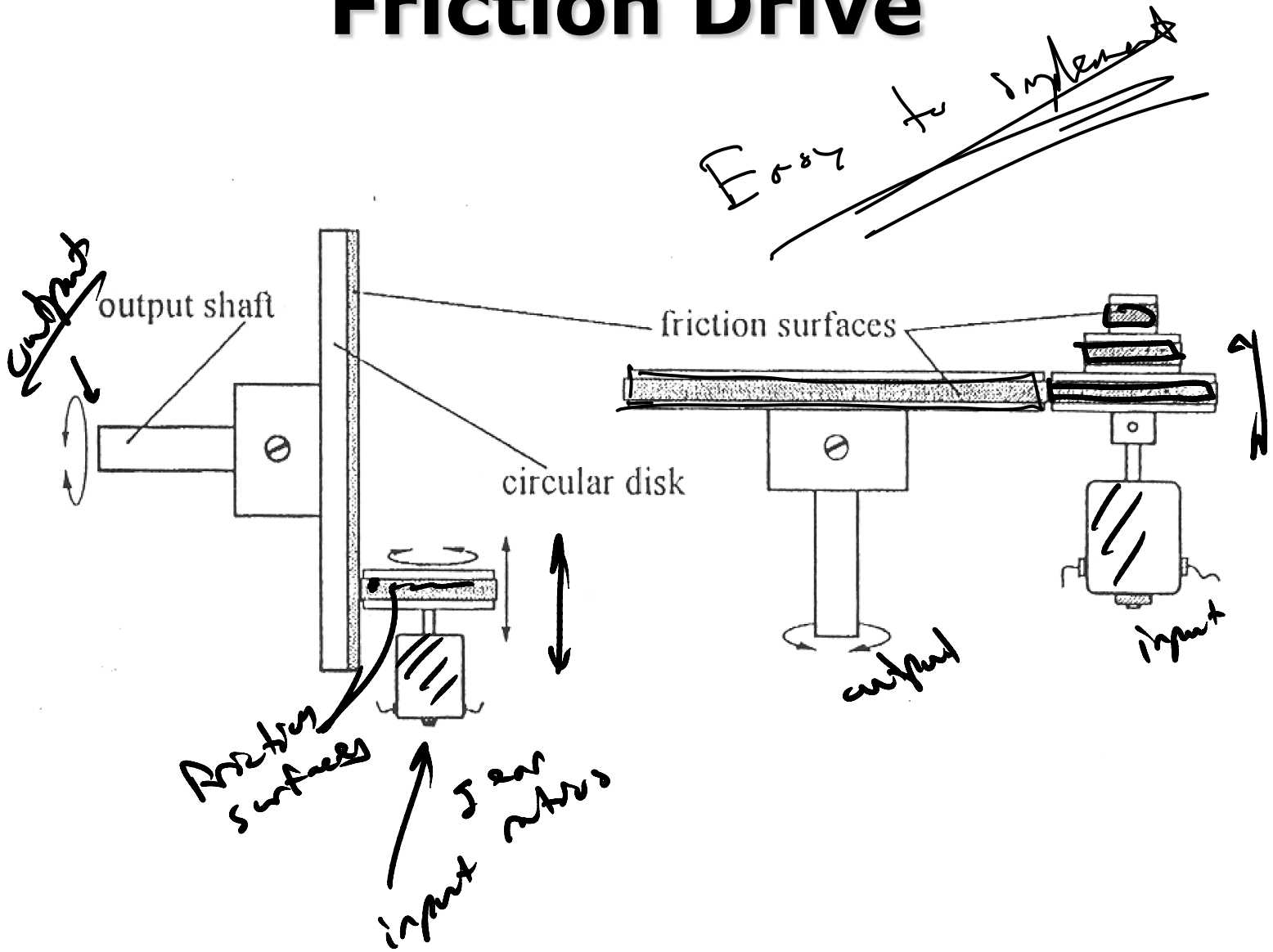
Belt

Gears

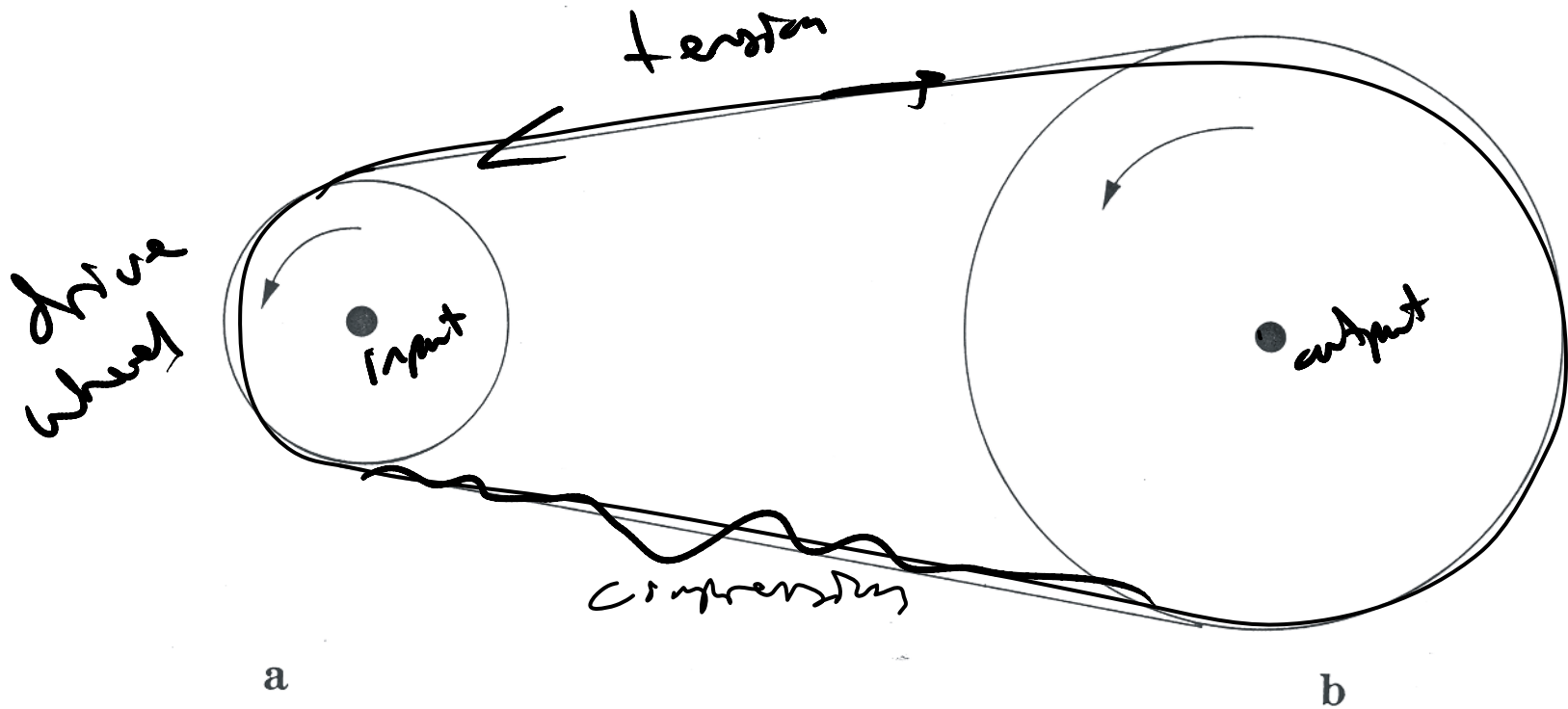
Direct — bolt onto end of motor



# Friction Drive



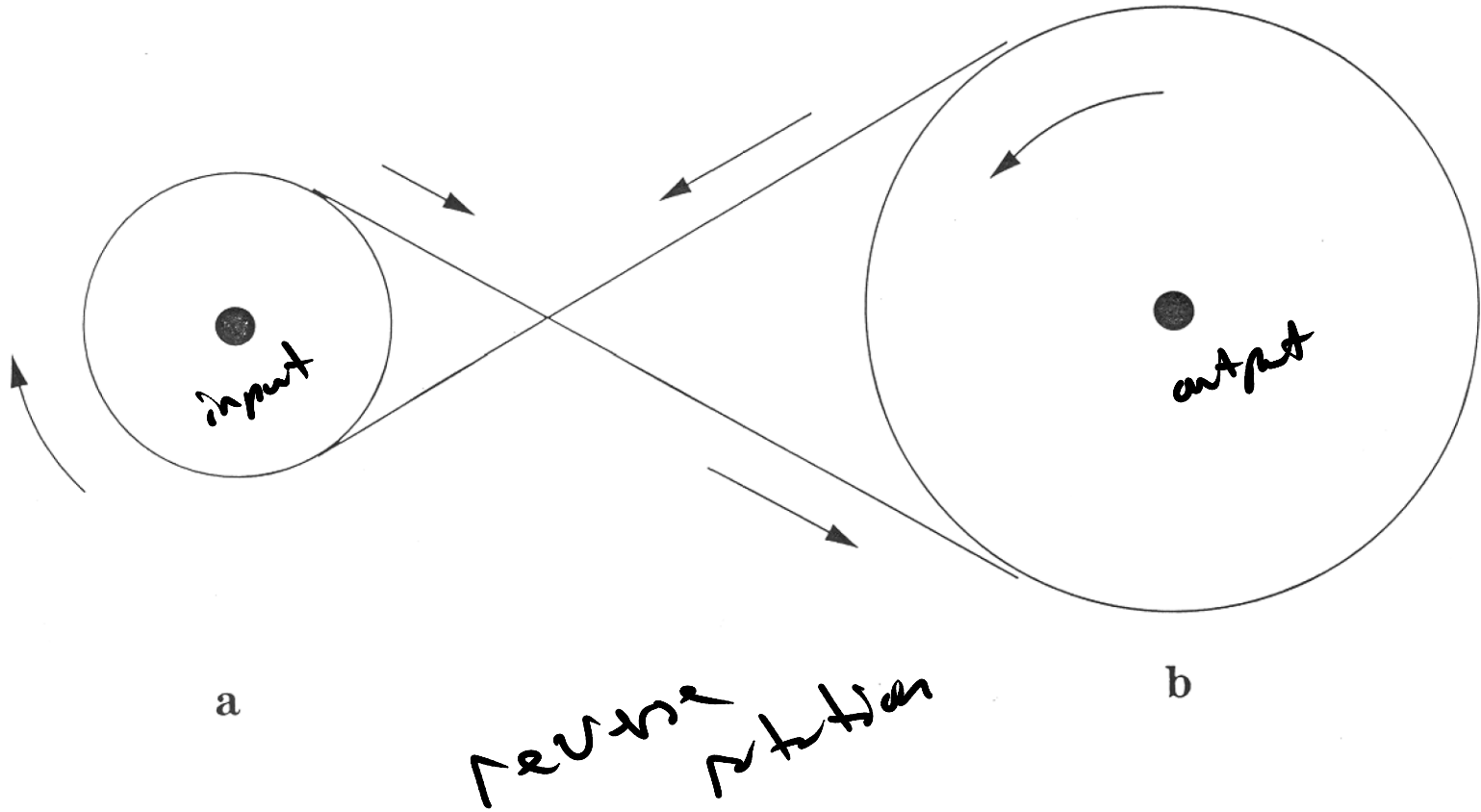
# Belt Drive (1.2)



pretty easy to make

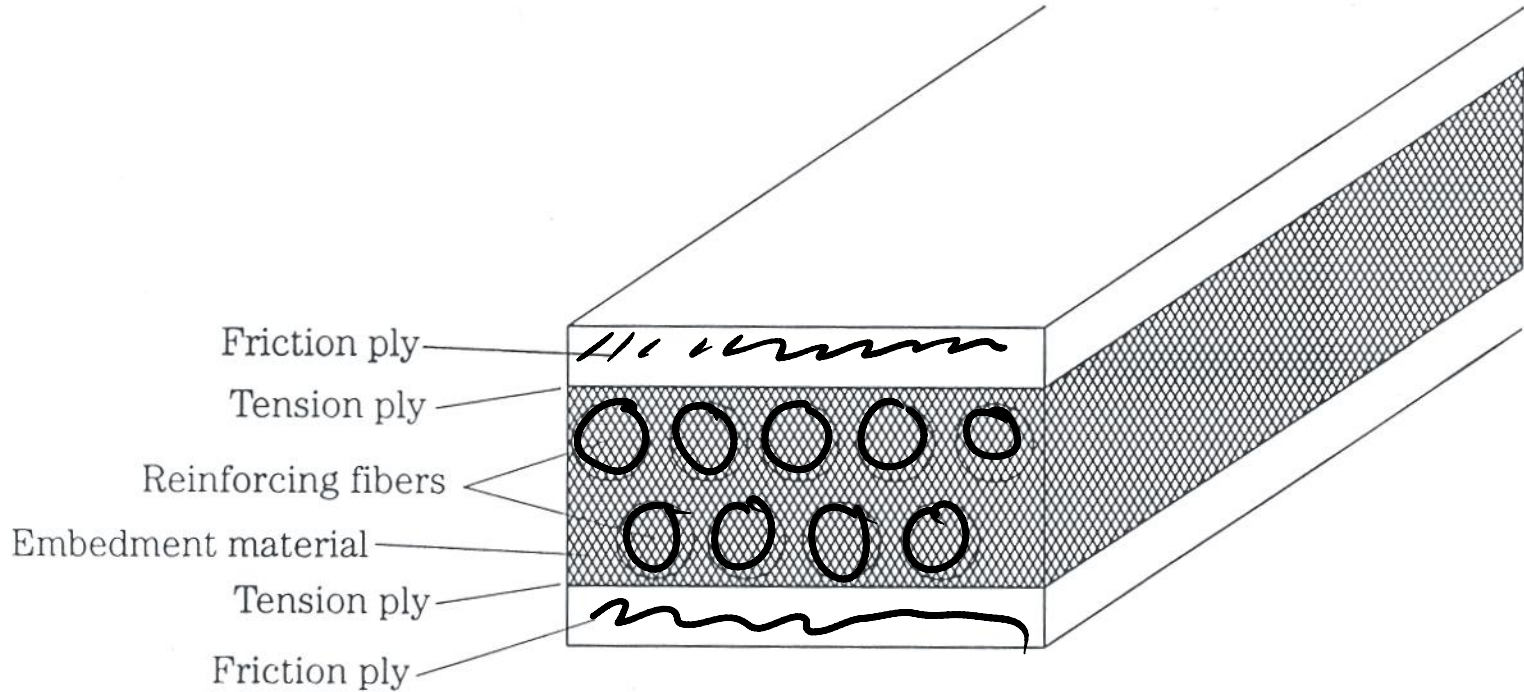


# Belt Drive (2.2)

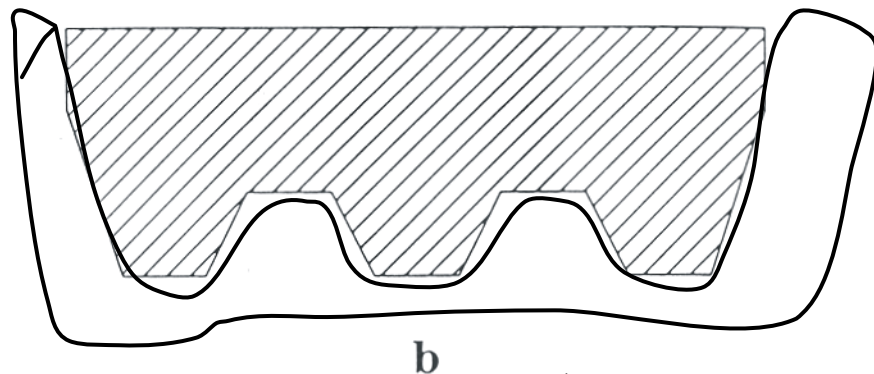
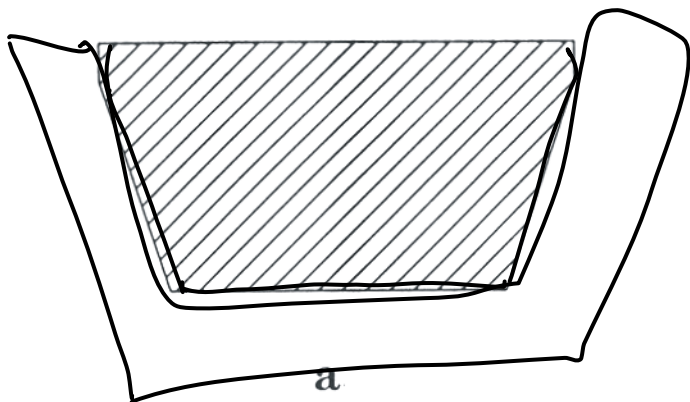




# Belt Drive Construction



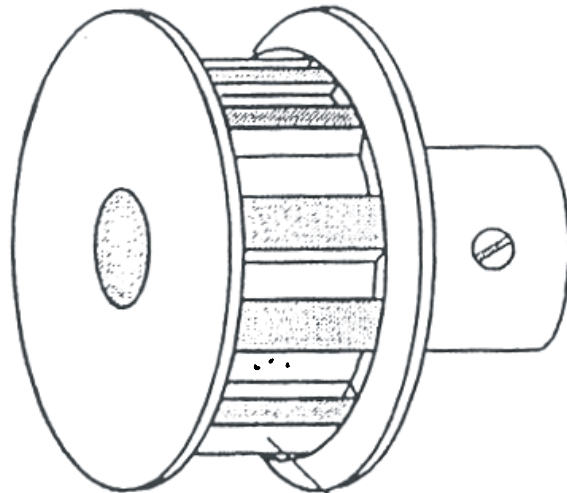
# Belt Profiles



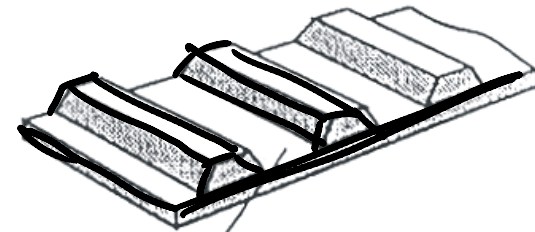
*Does not  
pull*



# Toothed Belt Drive



timing belt pulley



timing belt

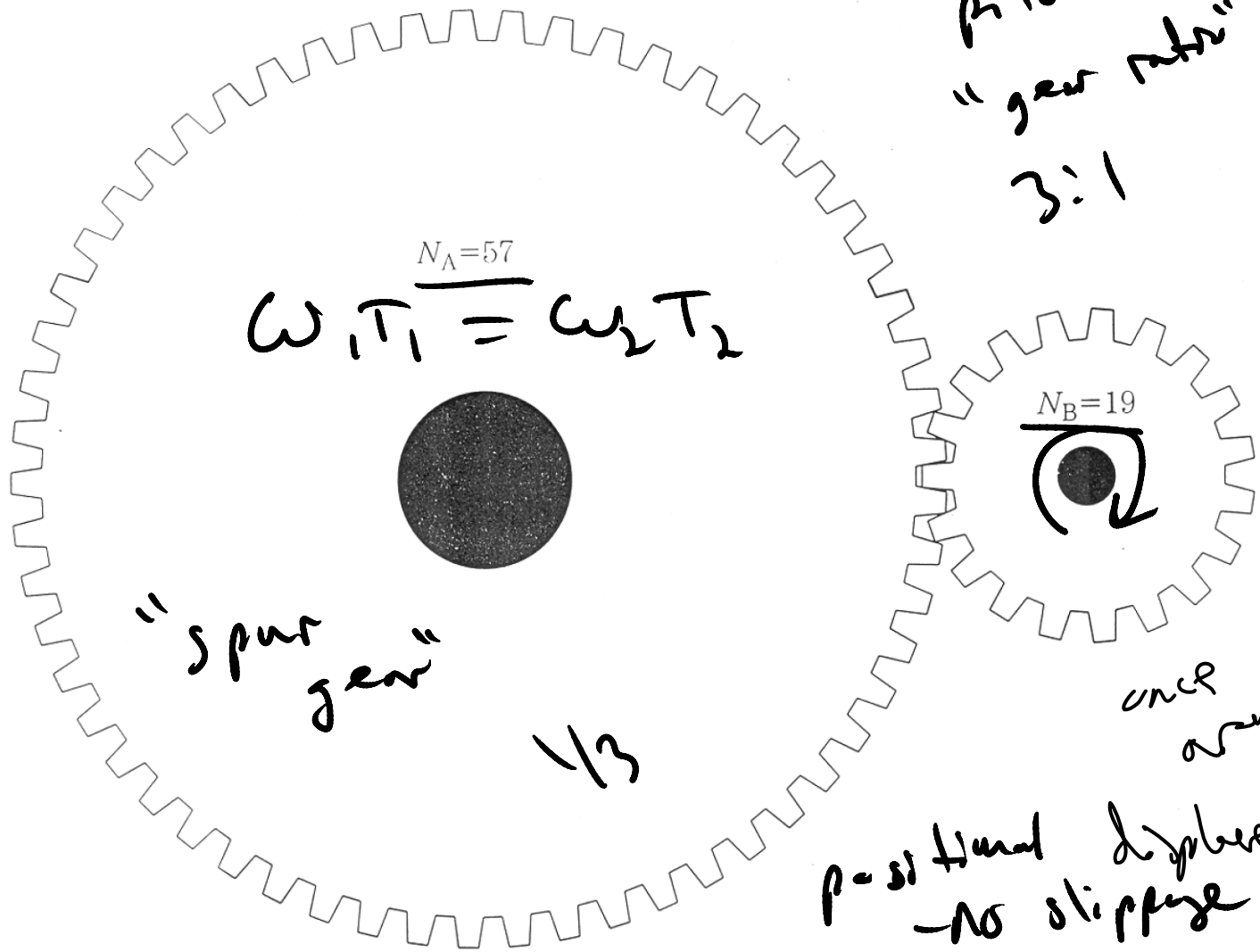


# Belt Drive on a HOG

- 120hp
- very quiet vs. chain
- little stretch
- no maintenance

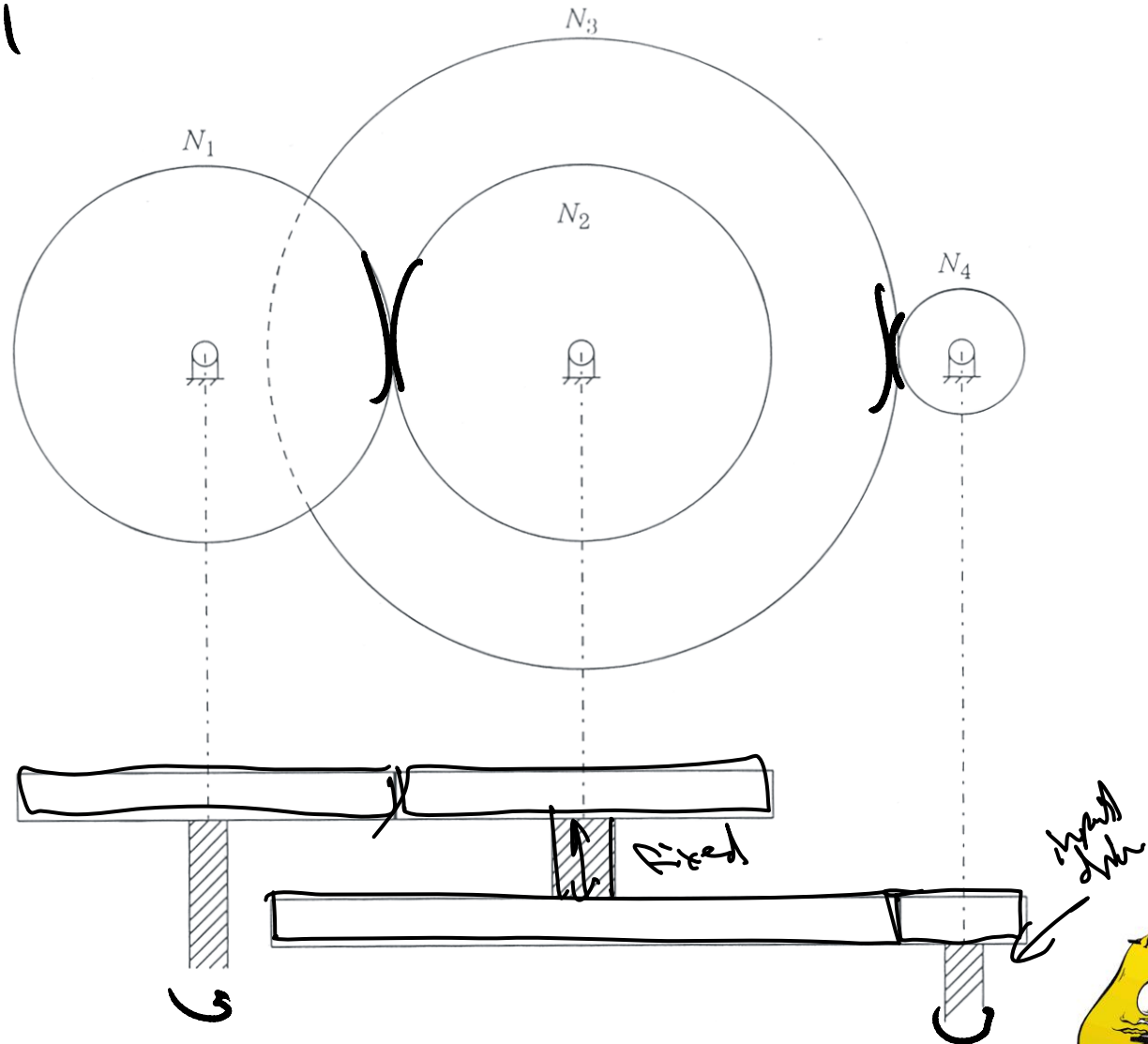


# Gear Drive

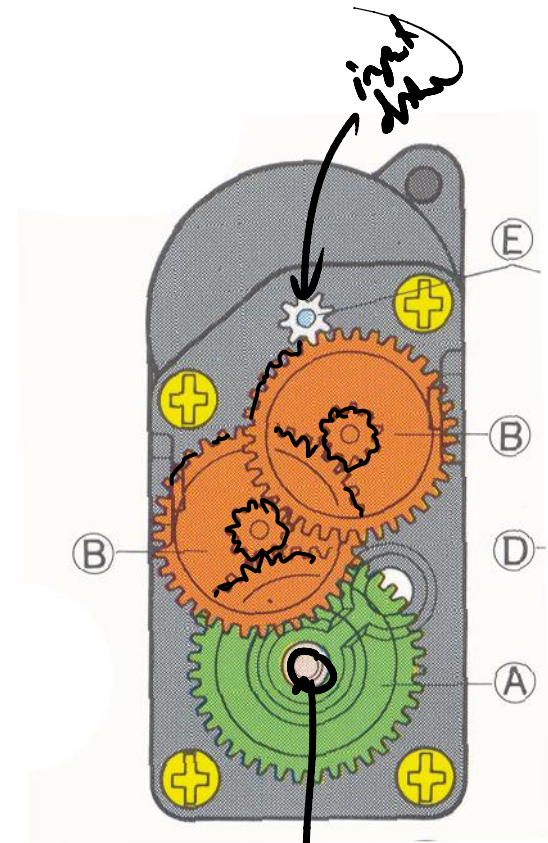
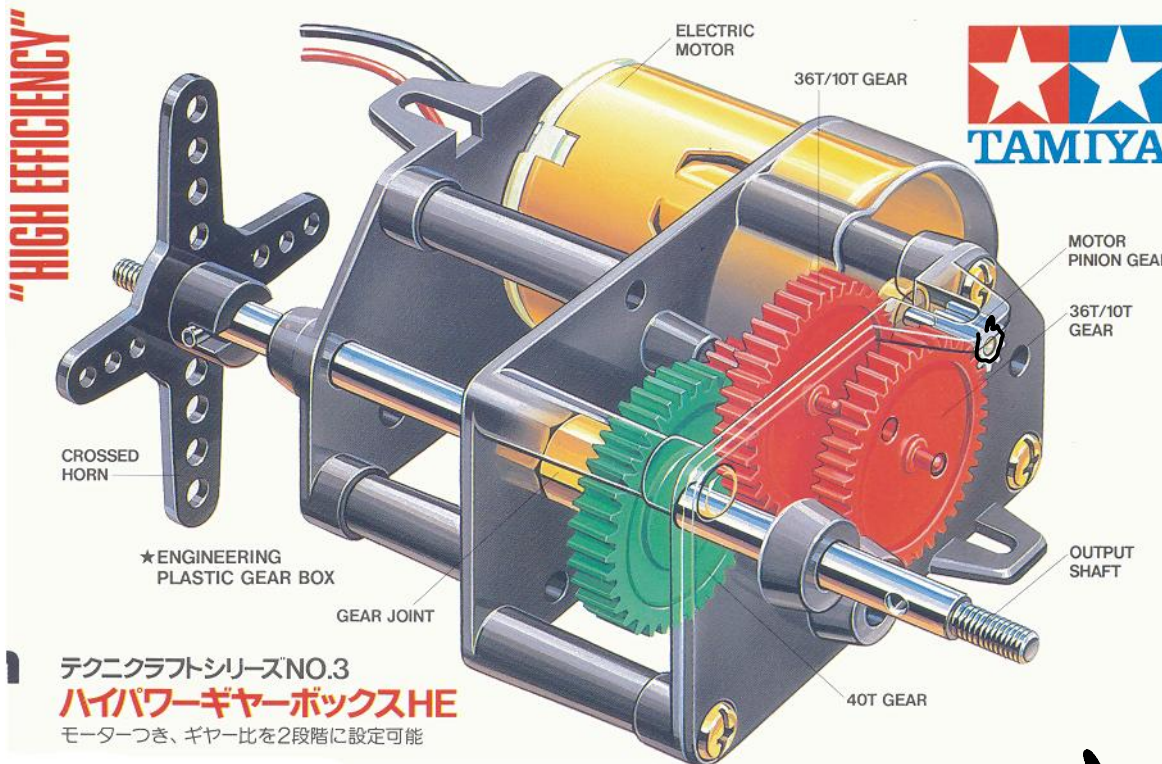


# Compound Gear Train (1.2)

$$1 \text{ rev } s - 1000 \text{ rev } s = 1$$



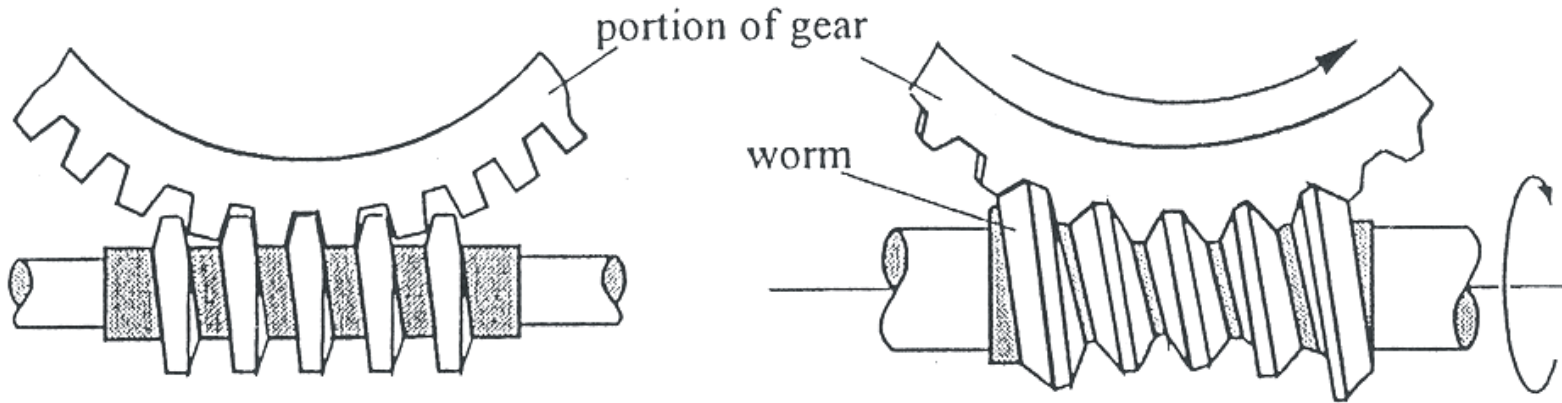
# Compound Gear Train (2.2)



64.8:1 } standard ratios  
 47:1



# Worm Drive (1.2)



(a)

(b)

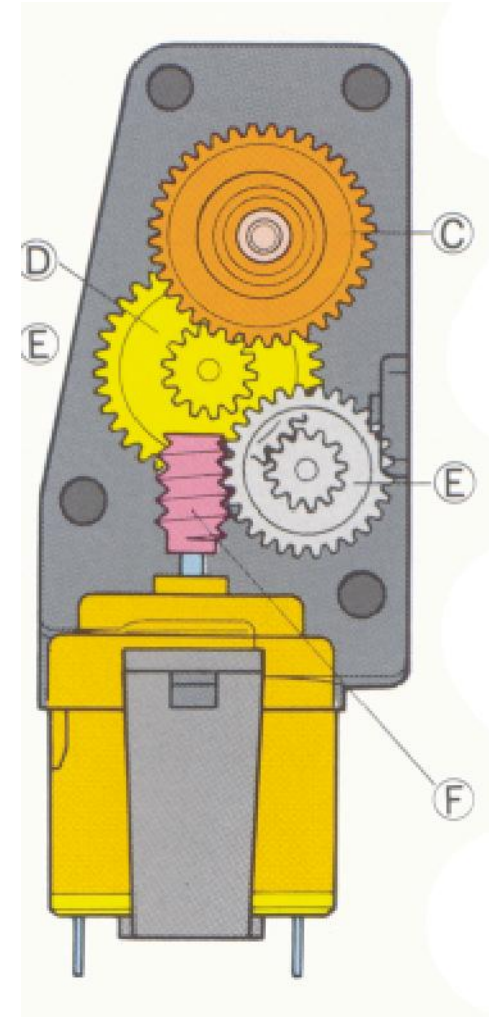
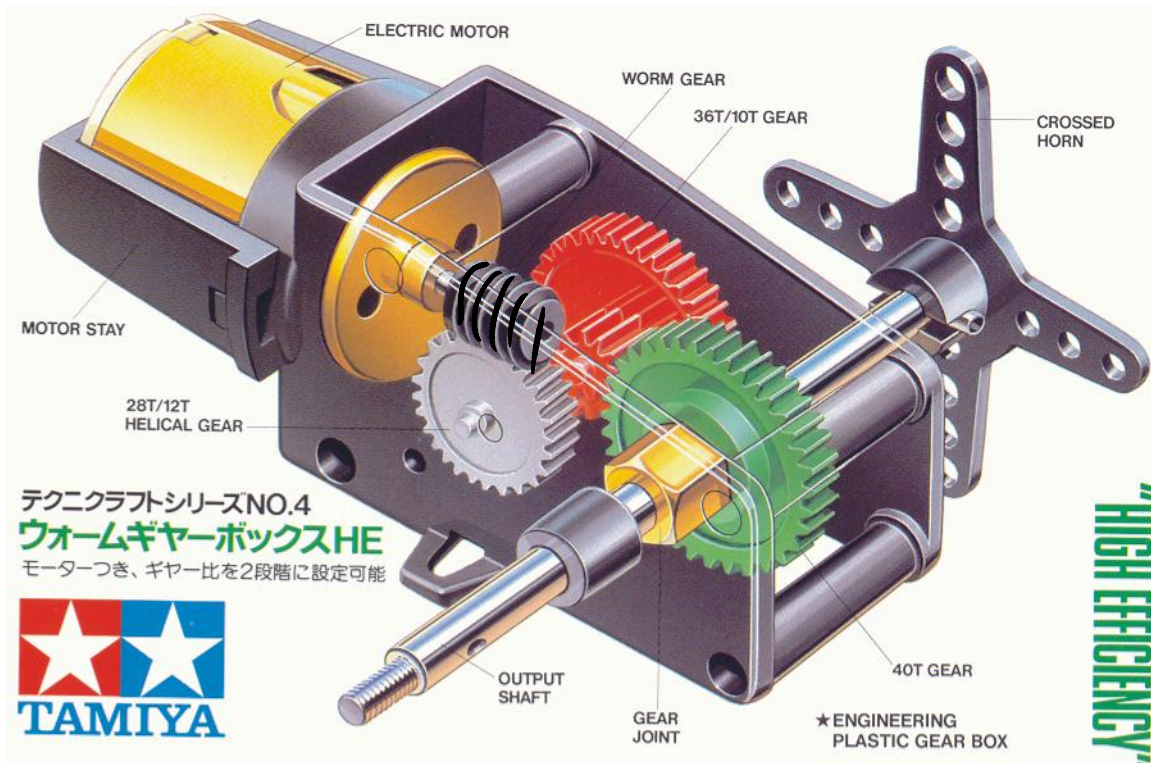
very high gear ratios

not usually backdrivable  
lock in place

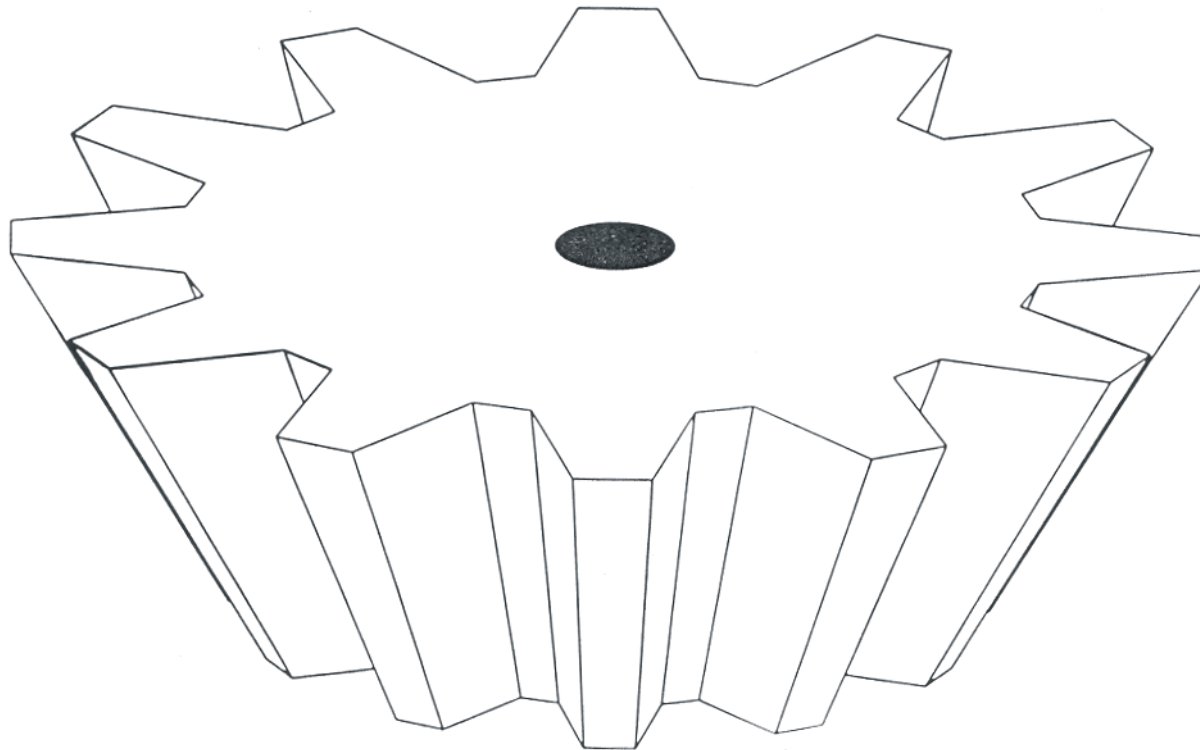




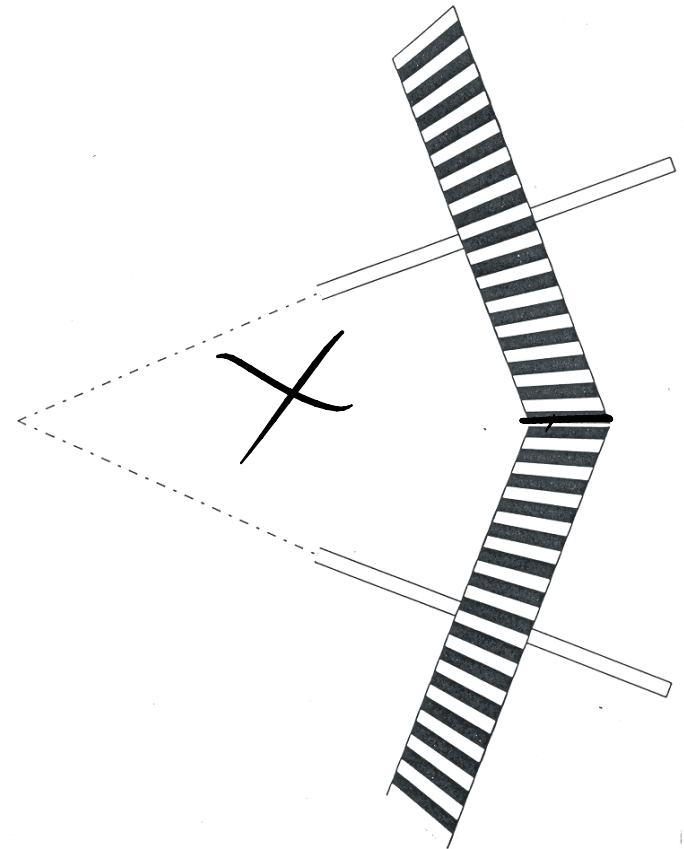
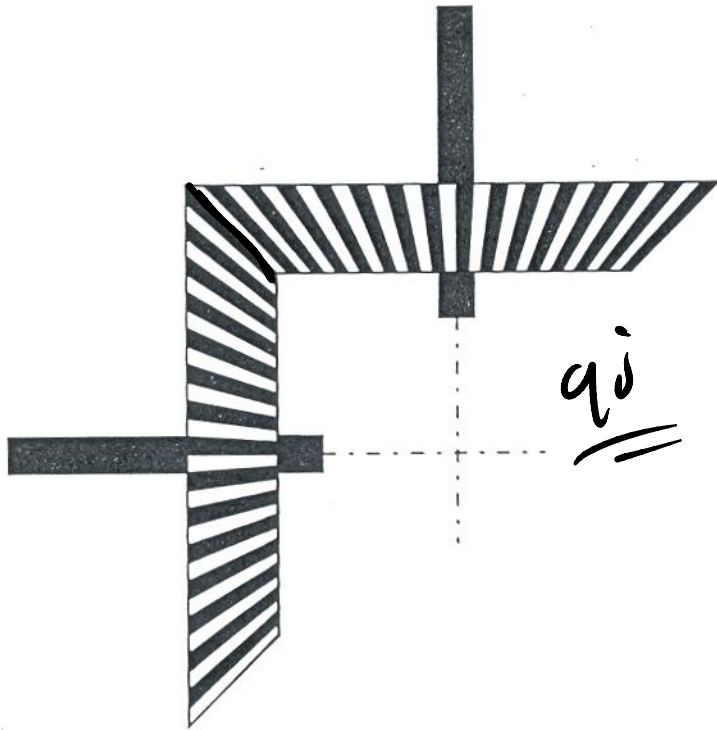
# Worm Drive (2.2)



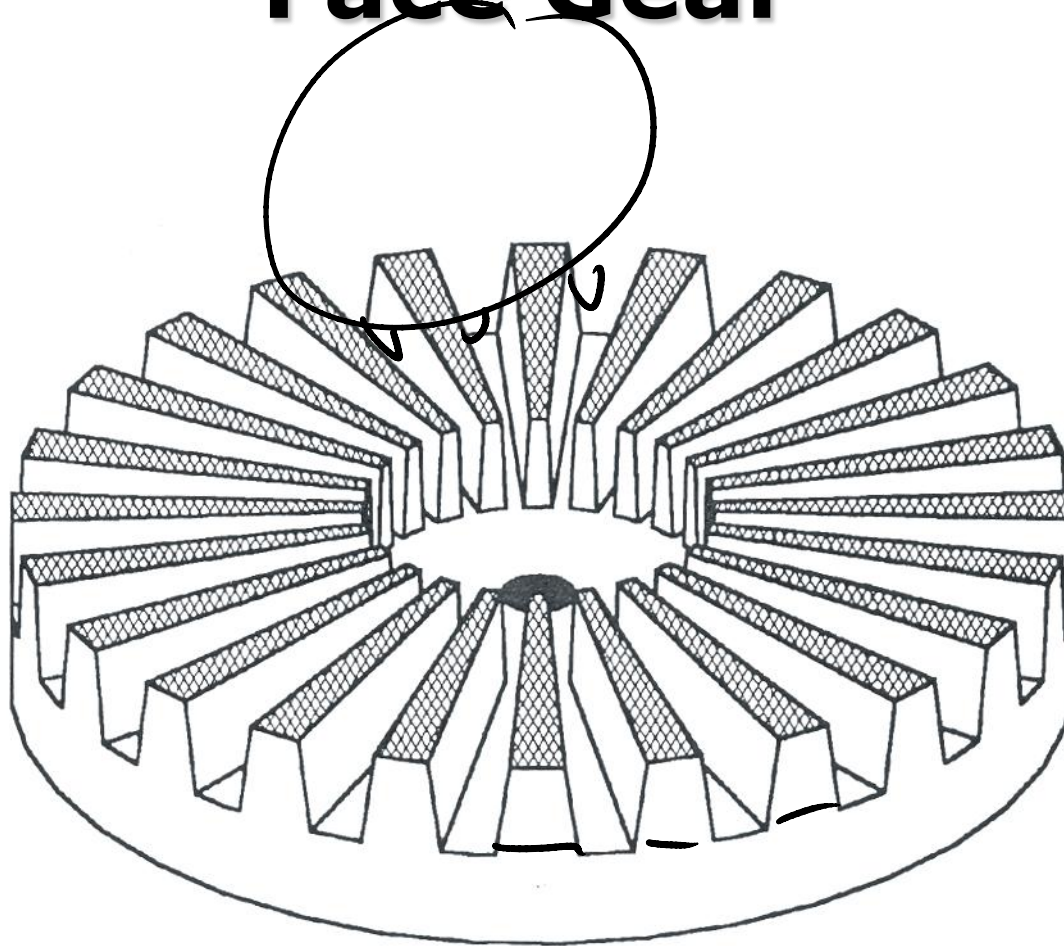
# Bevel Gear



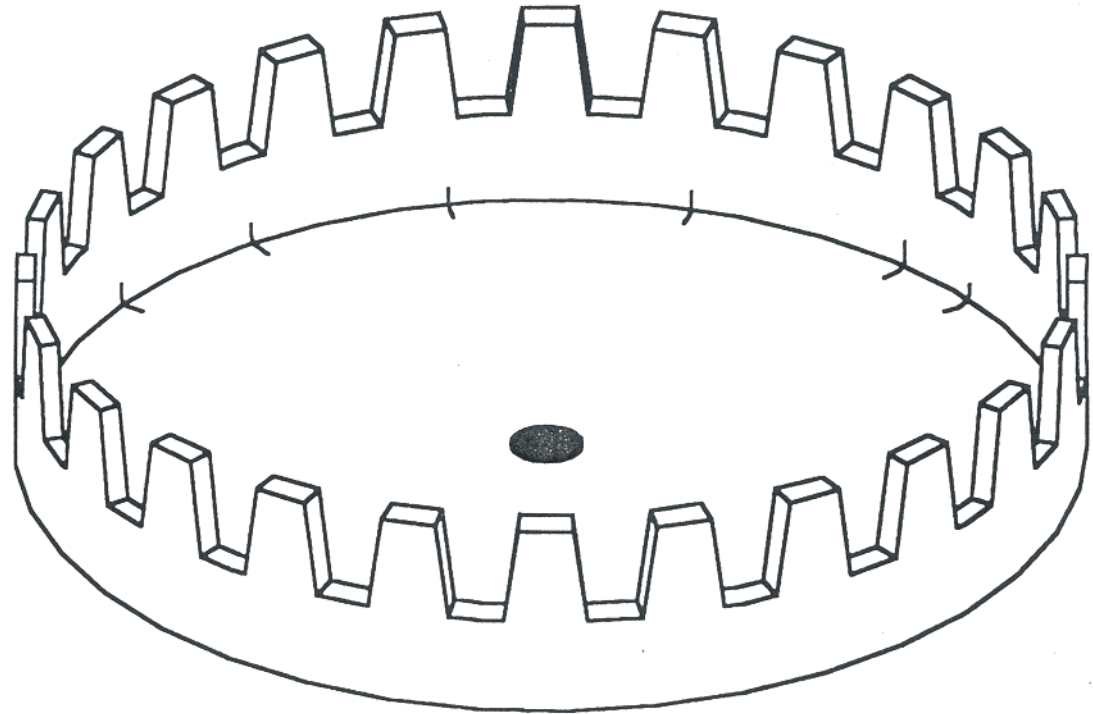
# Changing Direction of the Axis of Rotation



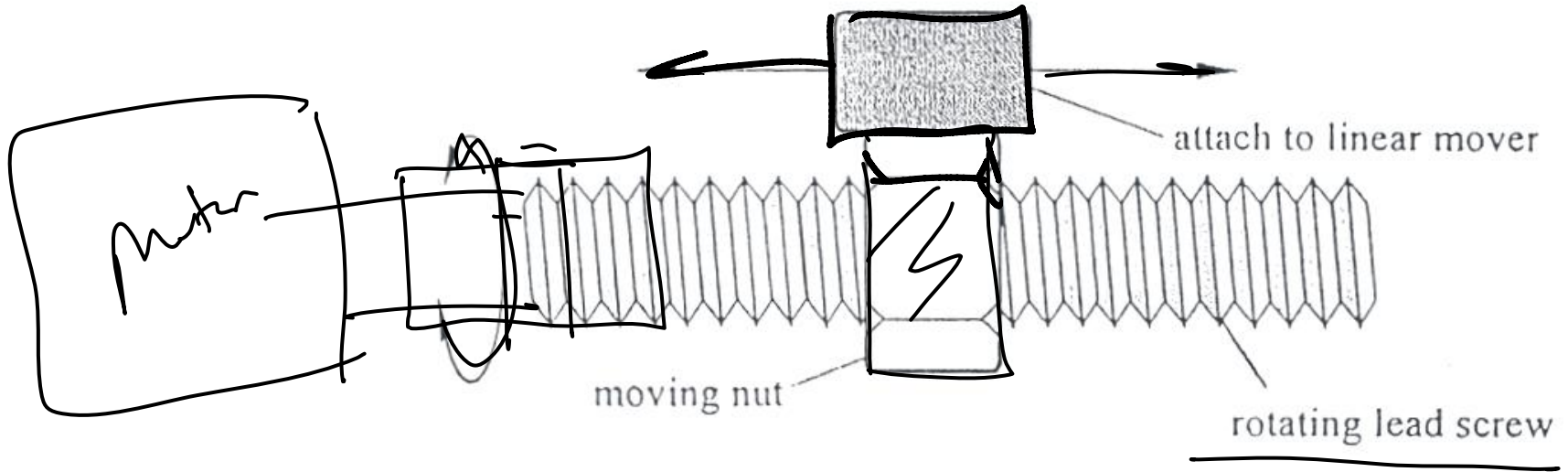
# Face Gear



# The Crown Gear



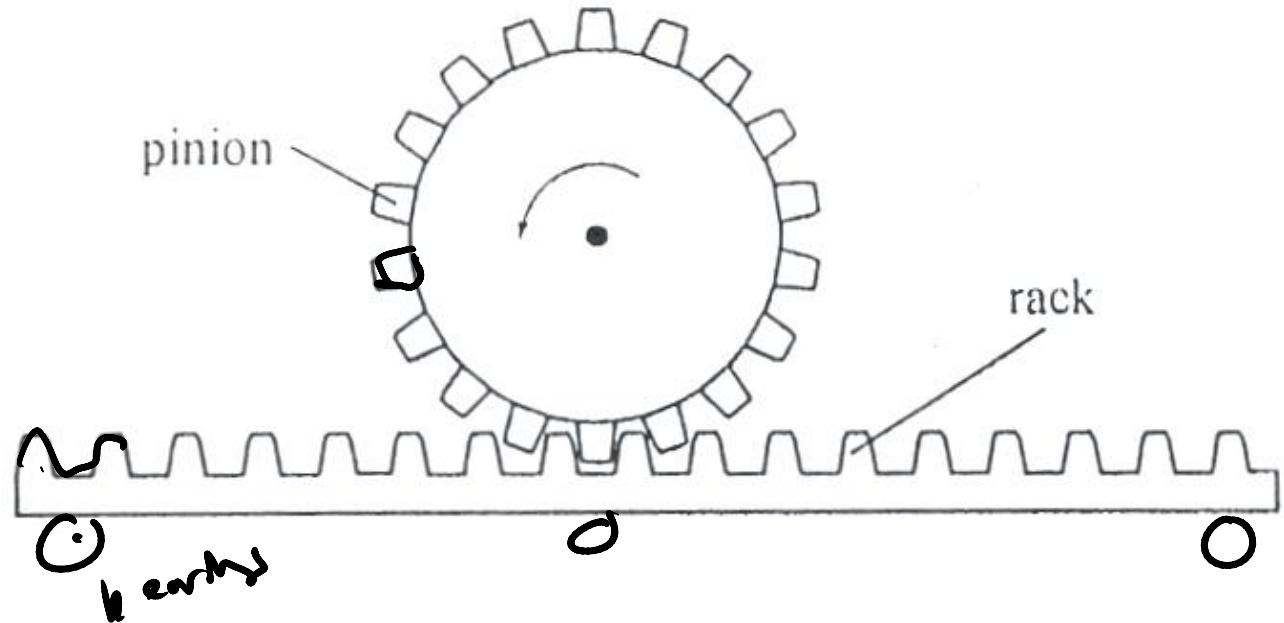
# Lead Screw Drive



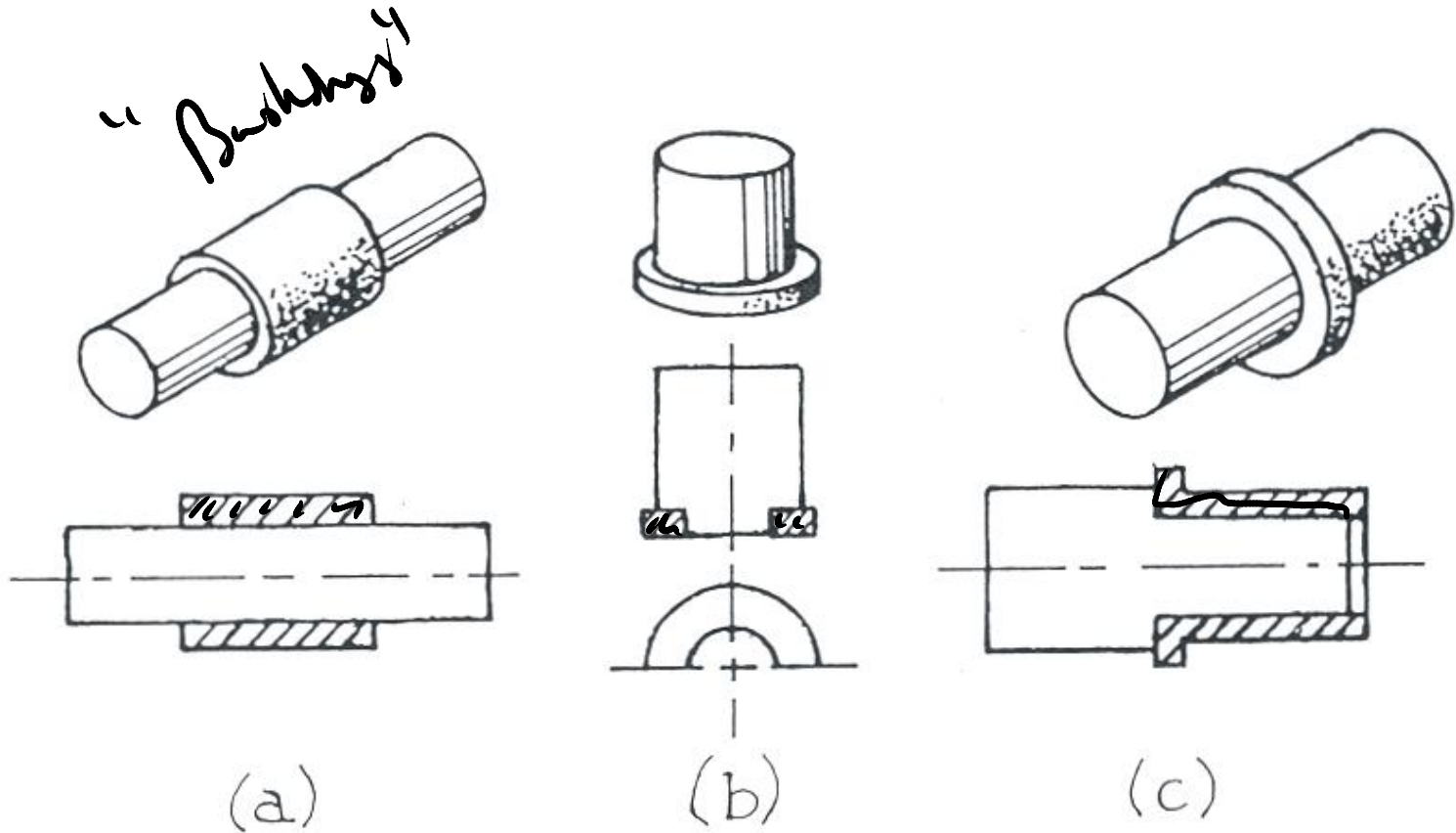
rotation → linear movement



# Rack and Pinion

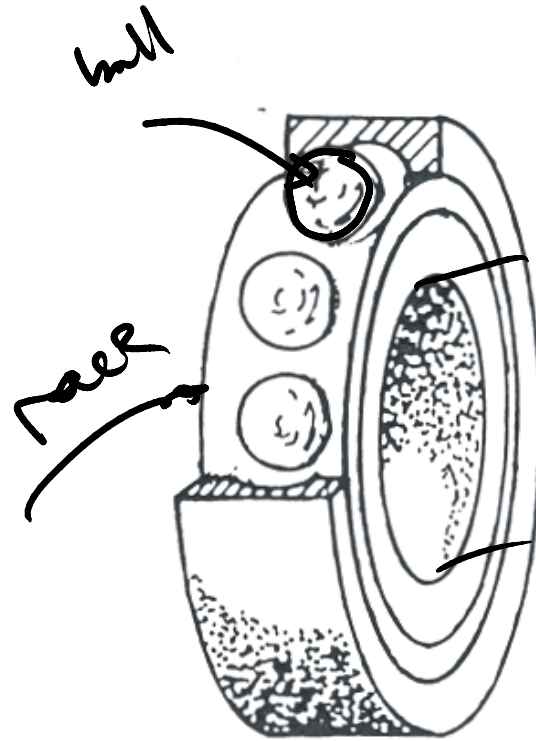


# Plain Bearings

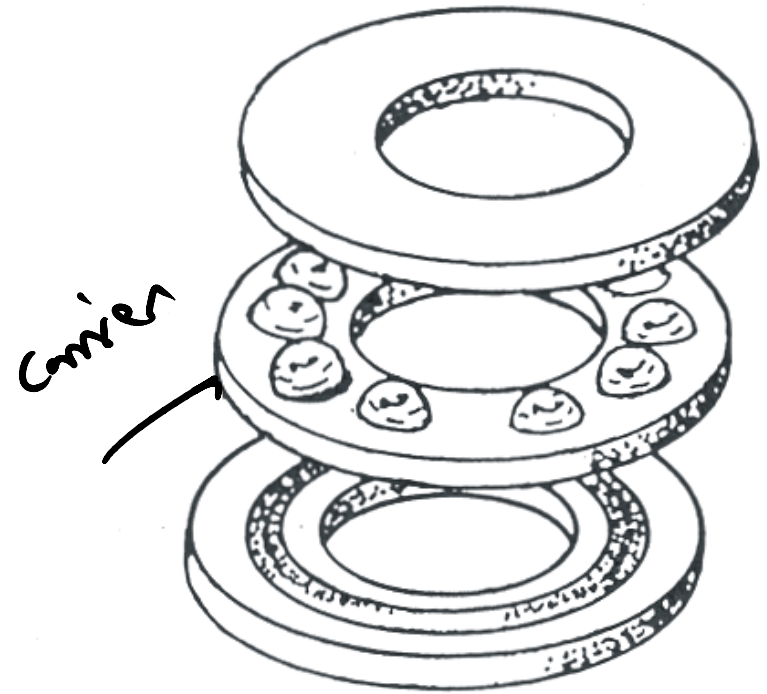




# Ball Bearings



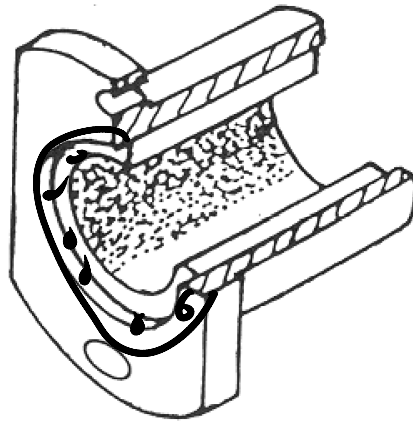
(a)



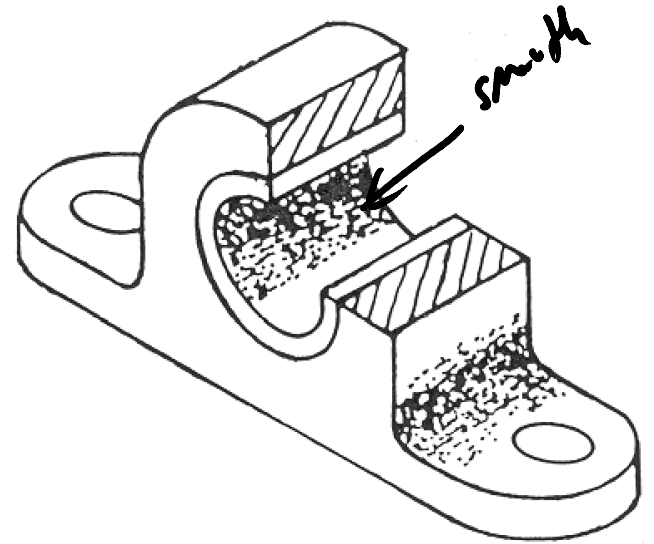
(b)



# Pillow Blocks



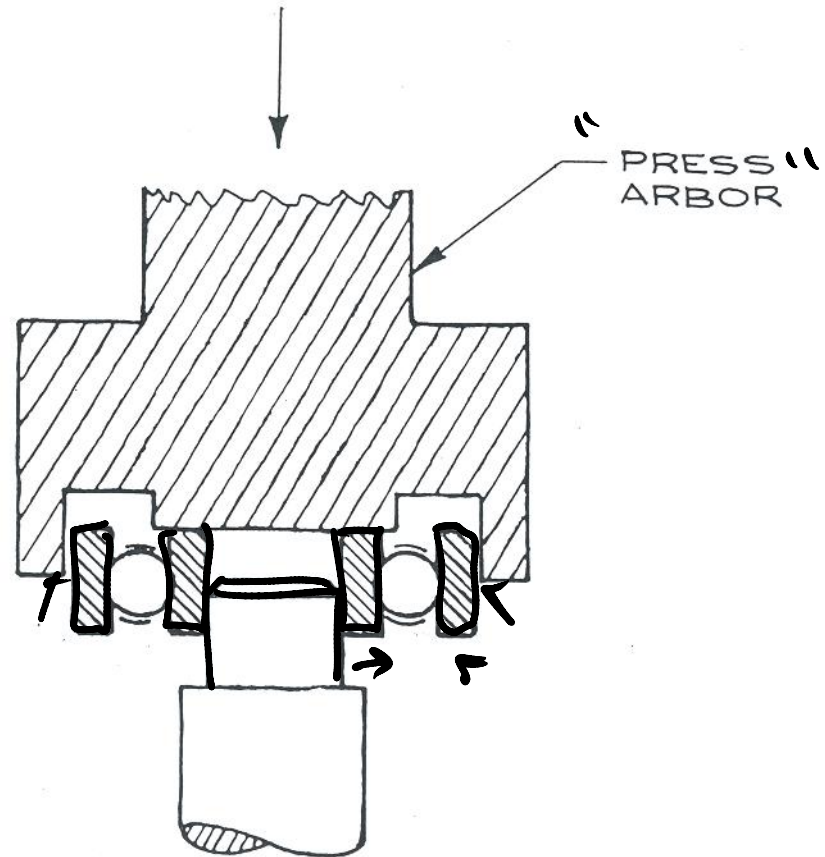
(a)



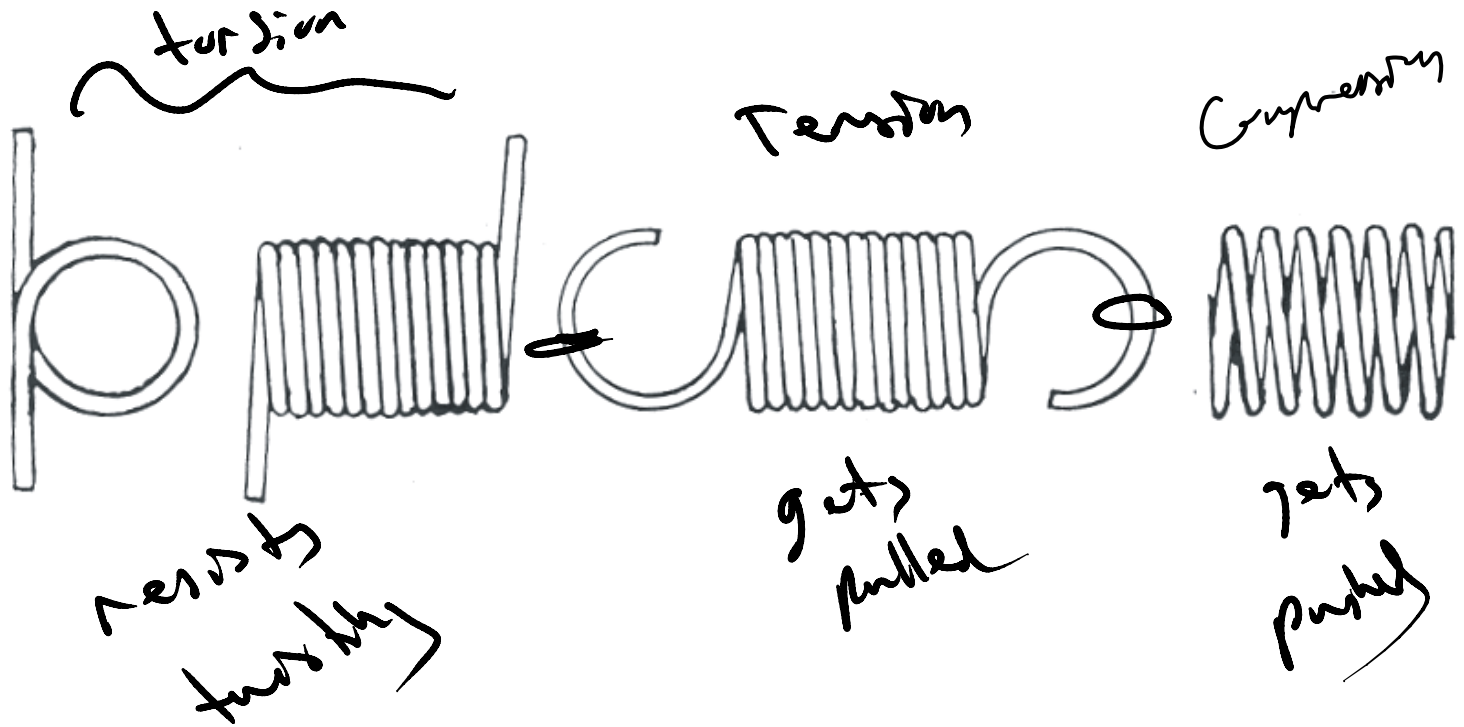
(b)



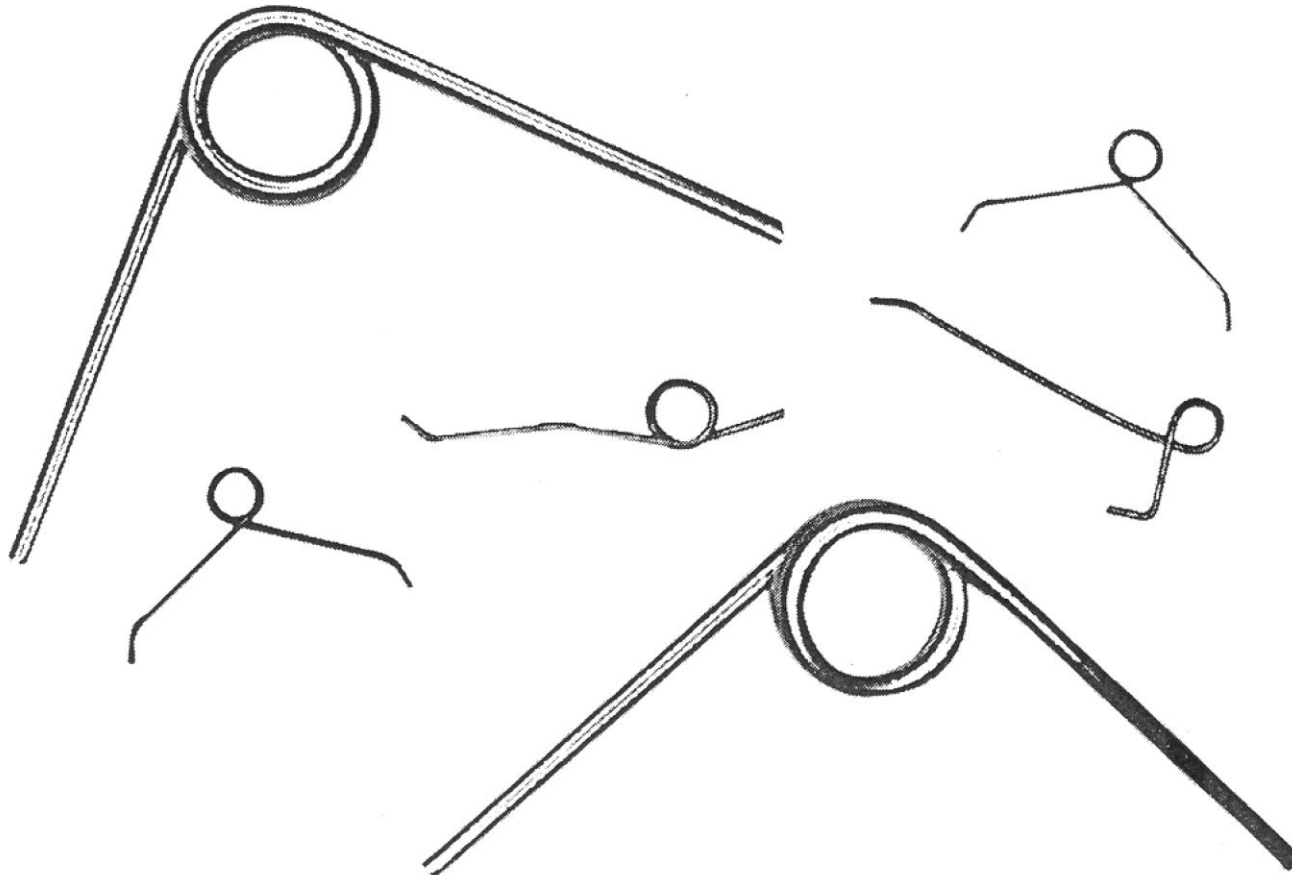
# Mounting Ball Bearings



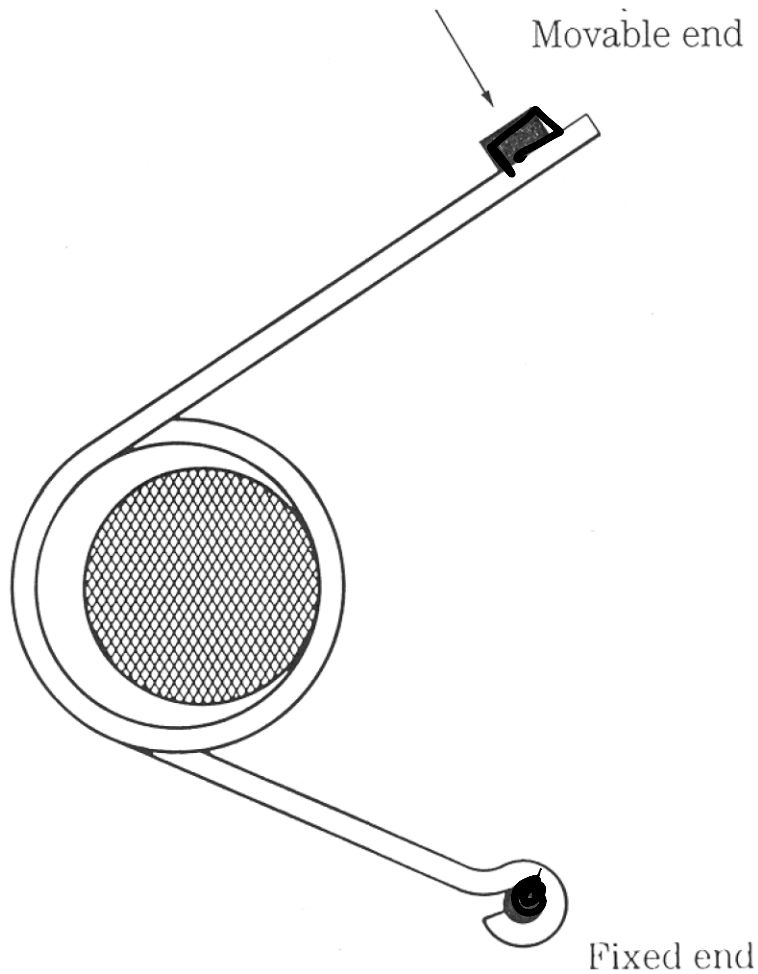
# Springs



# Helical Torsion Springs



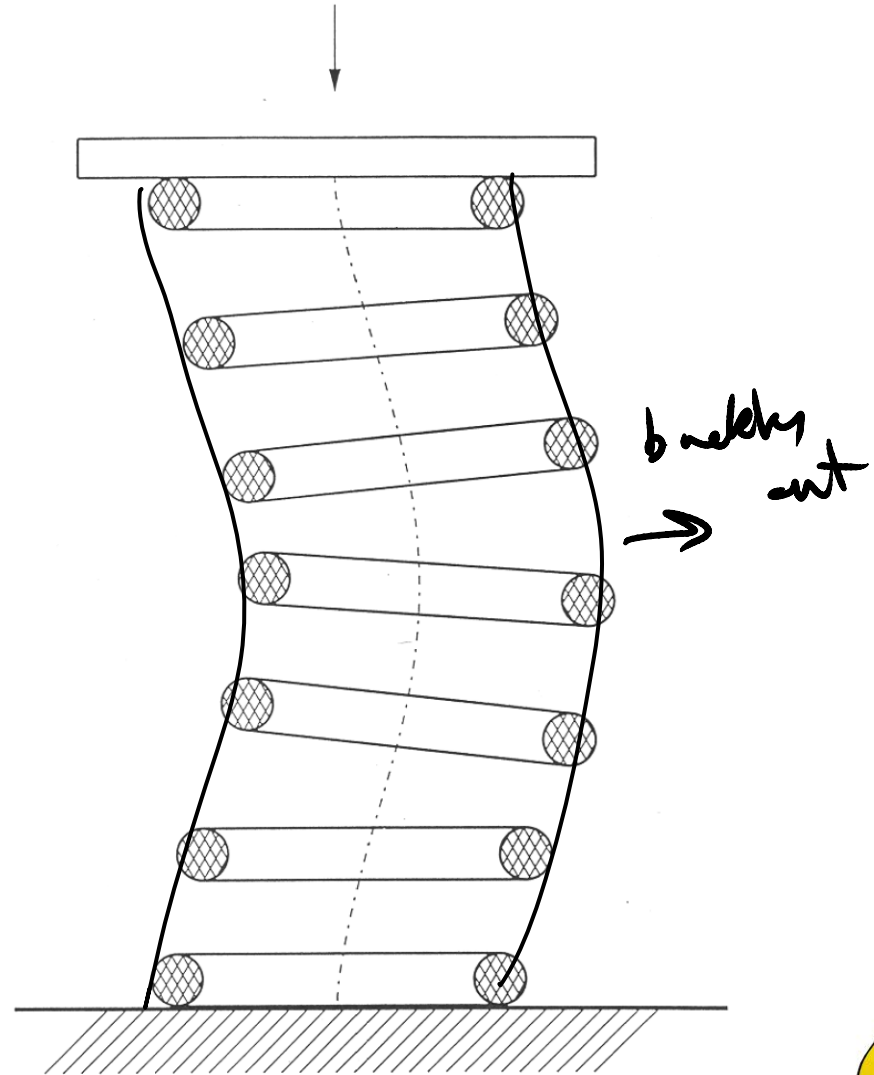
# Helical Torsion Spring Installation



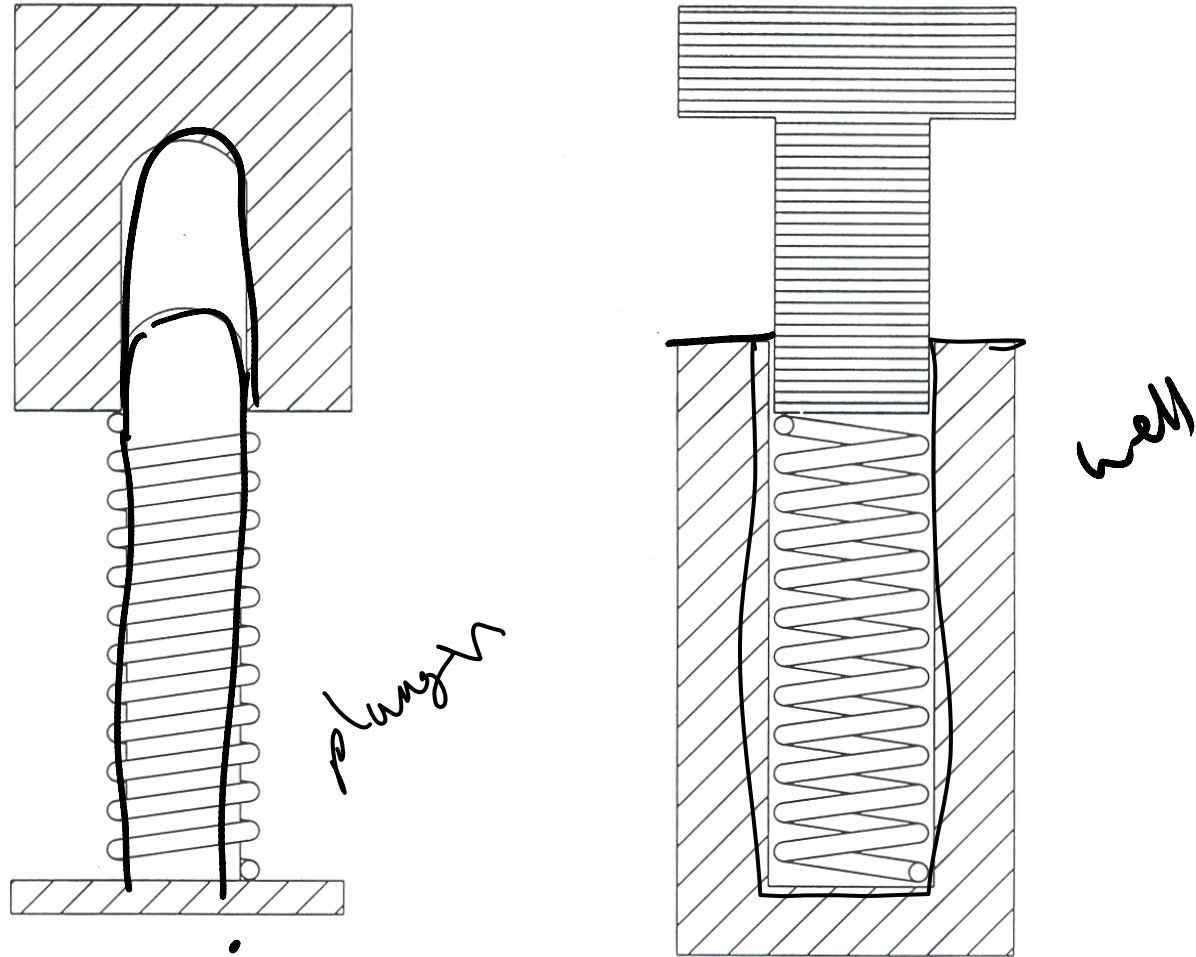
8-17  
Typical installation of a helical  
torsion spring.



# Distortion in Compression Springs



# Capturing a Compression Spring





# Questions?

